

BX-61-F3 Range

$I_0 = -0.502$

$I \in [-1.20, 0.70] \quad \Delta I = 1.9$

BS-61-F4 Range

$I_0 = 0.001$

Hysteresis

$I \in [-0.80, 1.50] \quad \Delta I = 2.3$

SY-57-3 Range

$I_0 = -0.499$

$I \in [-1.80, 0.90] \quad \Delta I = 2.7$

BY-61-F1 Range

$I_0 = 0.008$

$I \in [-0.492, 0.508] \quad \Delta I = 1.0$

$I \in [-0.5, +0.5]$

BY-61-F5 Range

$I_0 = -0.131$

$I \in [-0.83, 0.43] \quad \Delta I = 1.26$

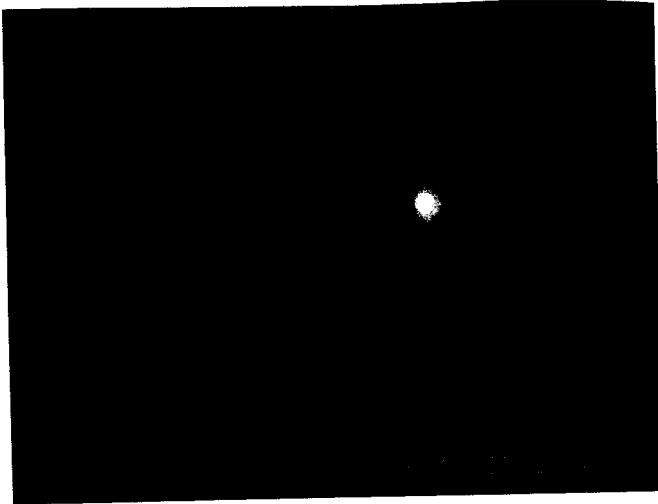
C-band STUDY 2005.10.25.

杉村, 紙谷

e⁻ 8 GeV ~~KEK~~ (KEKB e⁻モード), 5Hz, 5 Average.

工藤, 横山

軌道補正 3, 4, 5セクター (吉田さんプログラム)

SC
~~SP-61-H~~ ストリートスポット.Energy
フィードバック ~~OFF~~ ON.

SP-61-H1 offset.

0.08 → 0.00

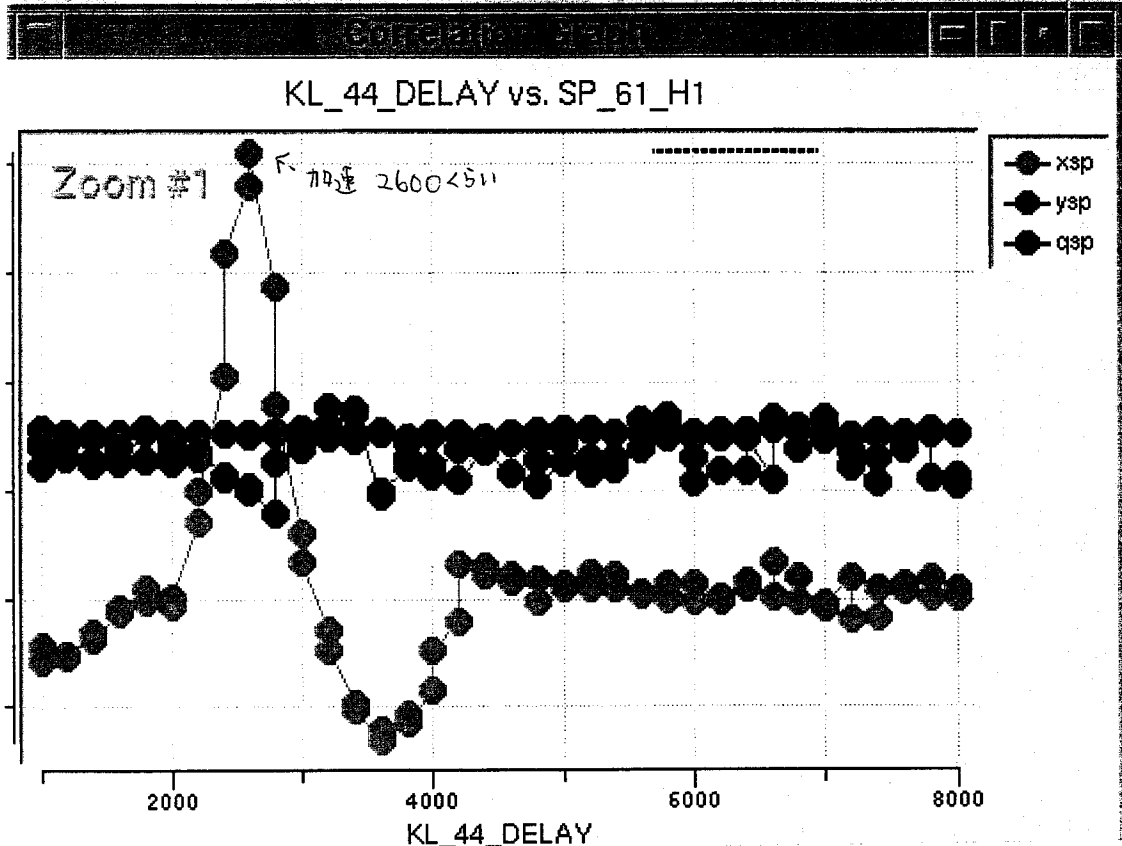
X(mm)	Y(mm)	I(nC)	dX(mm)	dY(mm)	dI(nC)
0.015	0.748	0.773	0.025	0.036	0.003
-0.02					

KEKB e- Energy Feedback is STOP, 5x is OFF

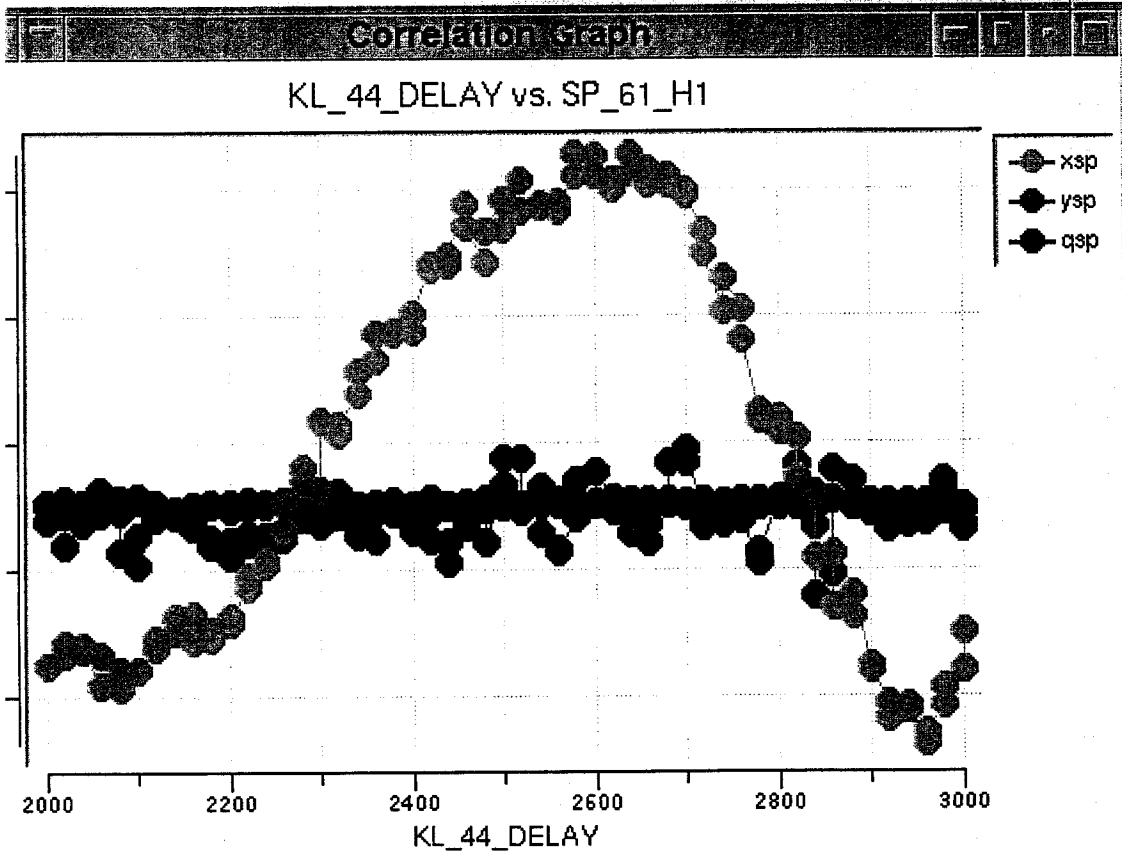
4-4. ACC ~~is~~ X(mm) → 0.08~~X(mm)~~~~is~~

KL-44-DELAY 3230 → 2600

① KL-44-DELAY
SP. 61-H1



1. KL-44-SB
- ② - DELAY
3. - WIDTH
4. - PHASE



PHASE

371.2° → 191.2° → 150°
 2.0 -2.0 -3.0

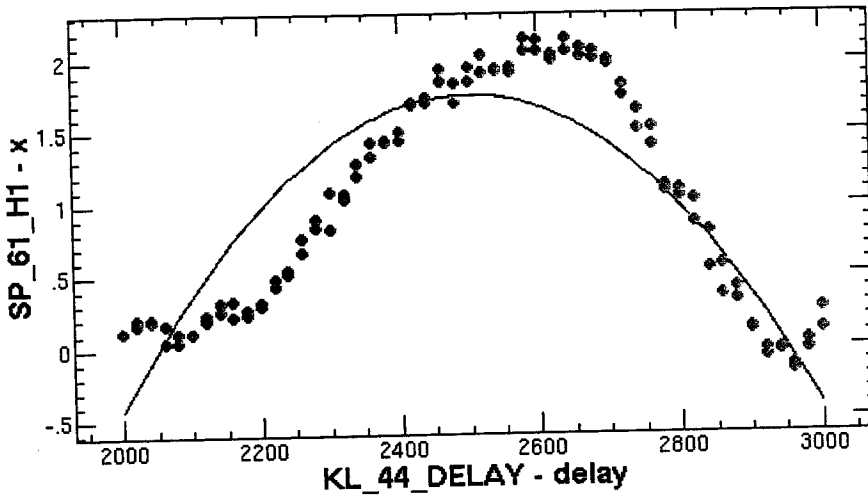
Error messageの時

Kly-Phase A

File Edit Window

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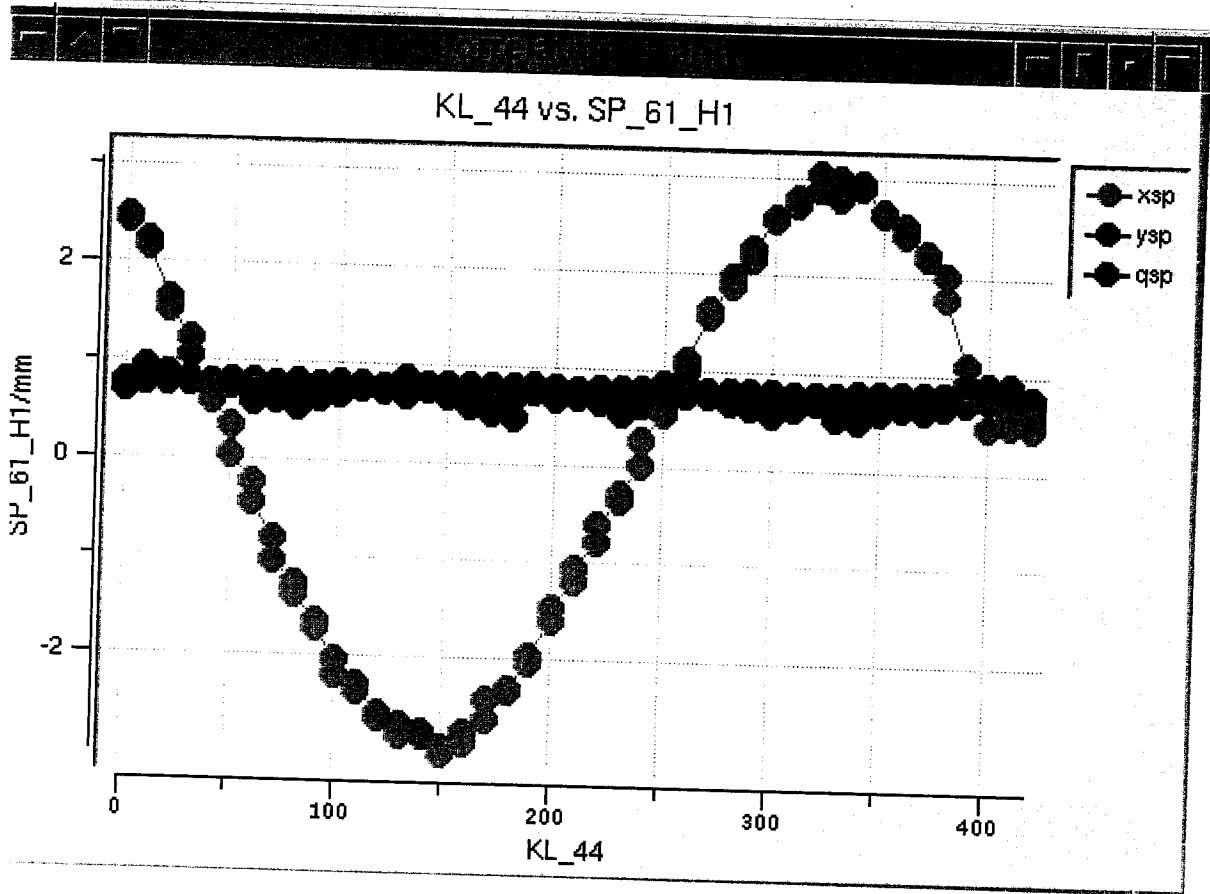
ChiSquare = 13.5825 Goodness = .48110
 a = -8.7E-6 +/- 4.73E-7 b = 2500.00 +/- 7.12788 c = 1.75561 +/- .05503



Function = (c+(a ((x+(-b))^2)))

Main Application Area

* delay は 3,000 以上はいいません。



File Edit Window

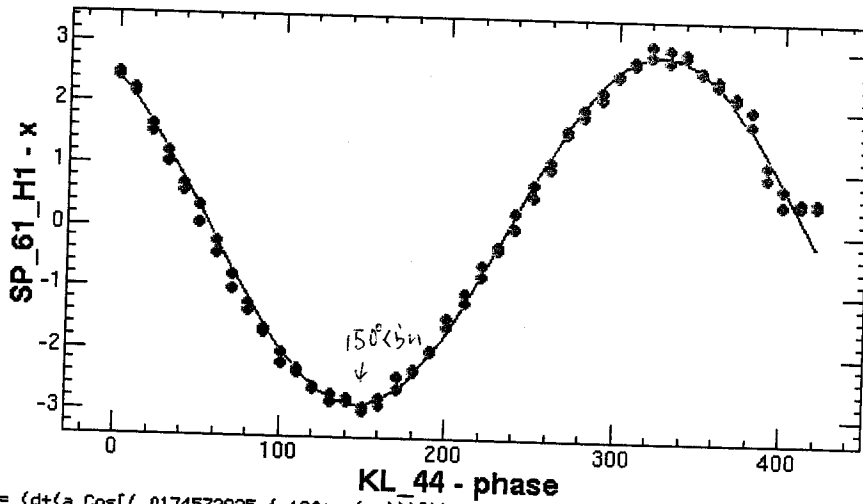
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ChiSquare = 2.52821 Goodness = .47935

a = 2.87727 +/- .02795

c = 145.754 +/- .52140

d = .00746 +/- .01922

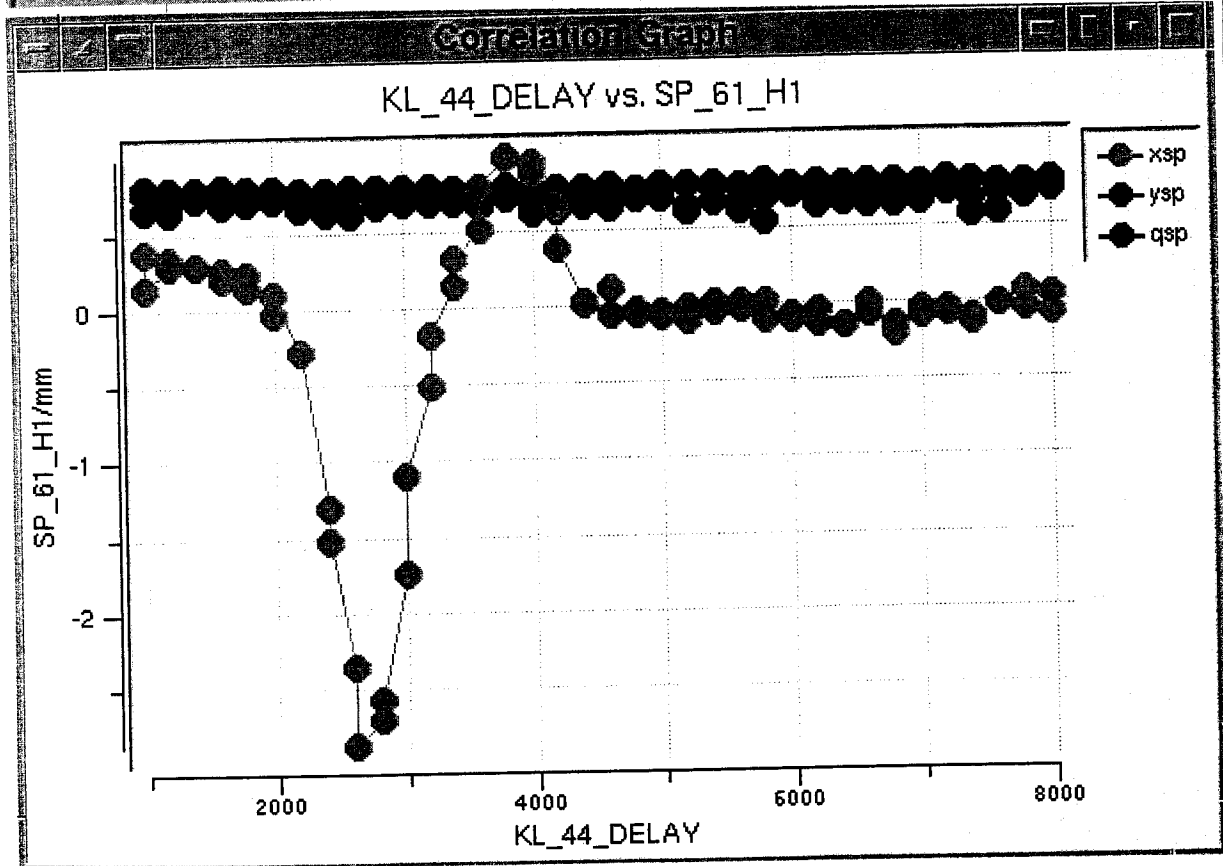
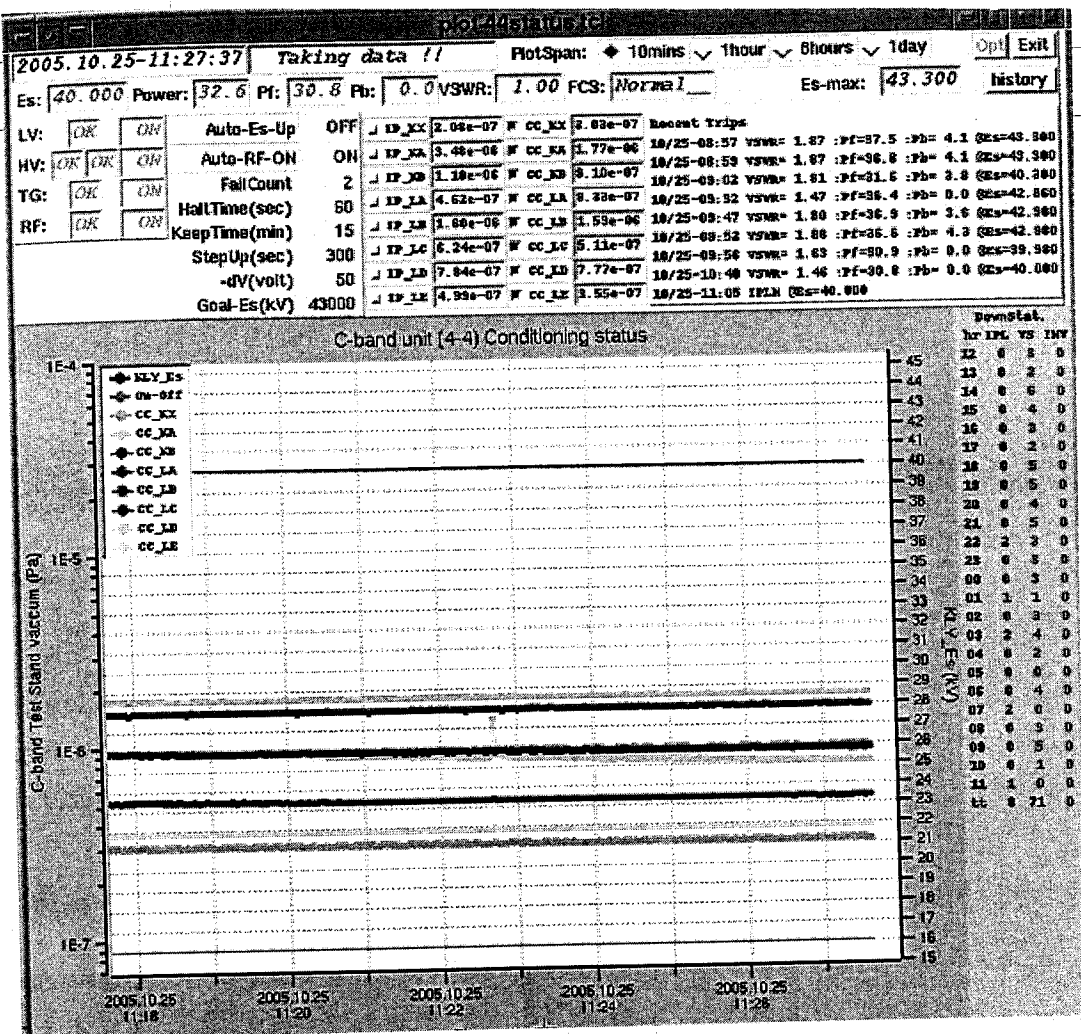


motion = (d+(a Cos[(.0174532925 (-180+x+(-c))])))

in Application Area

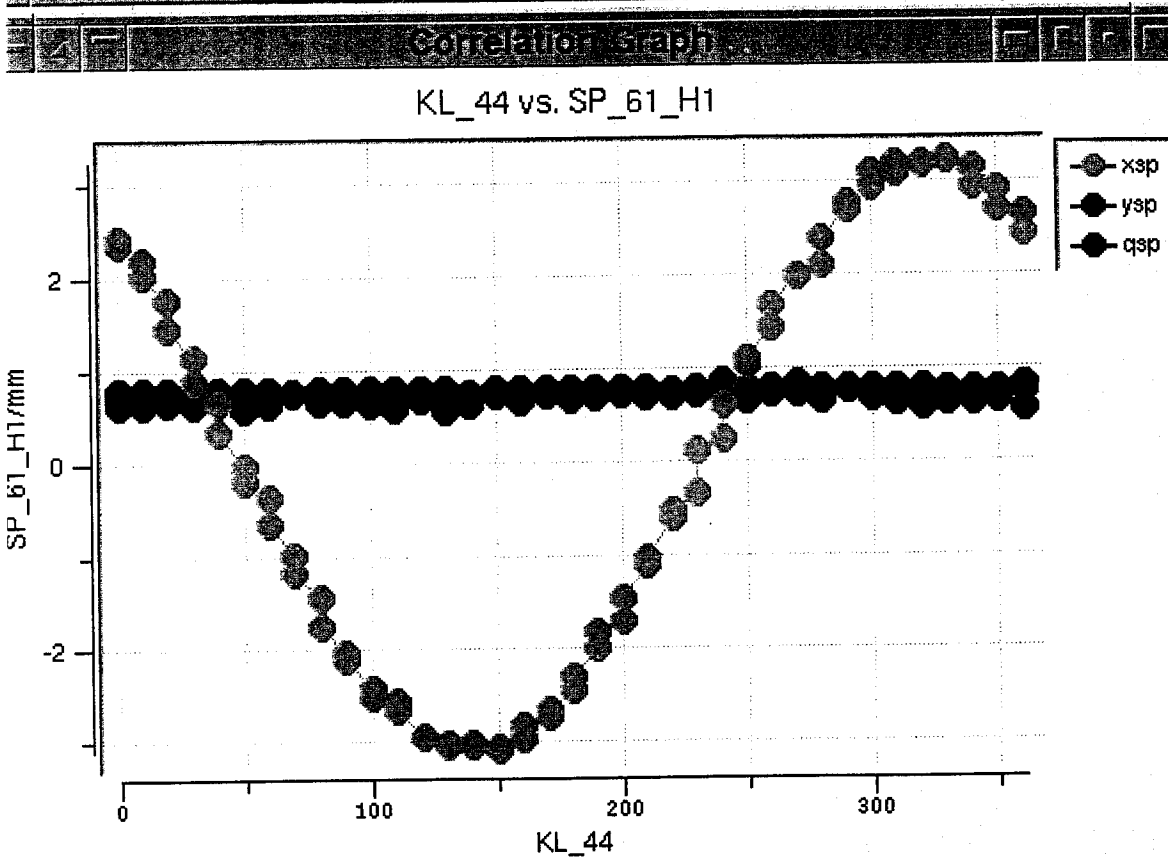
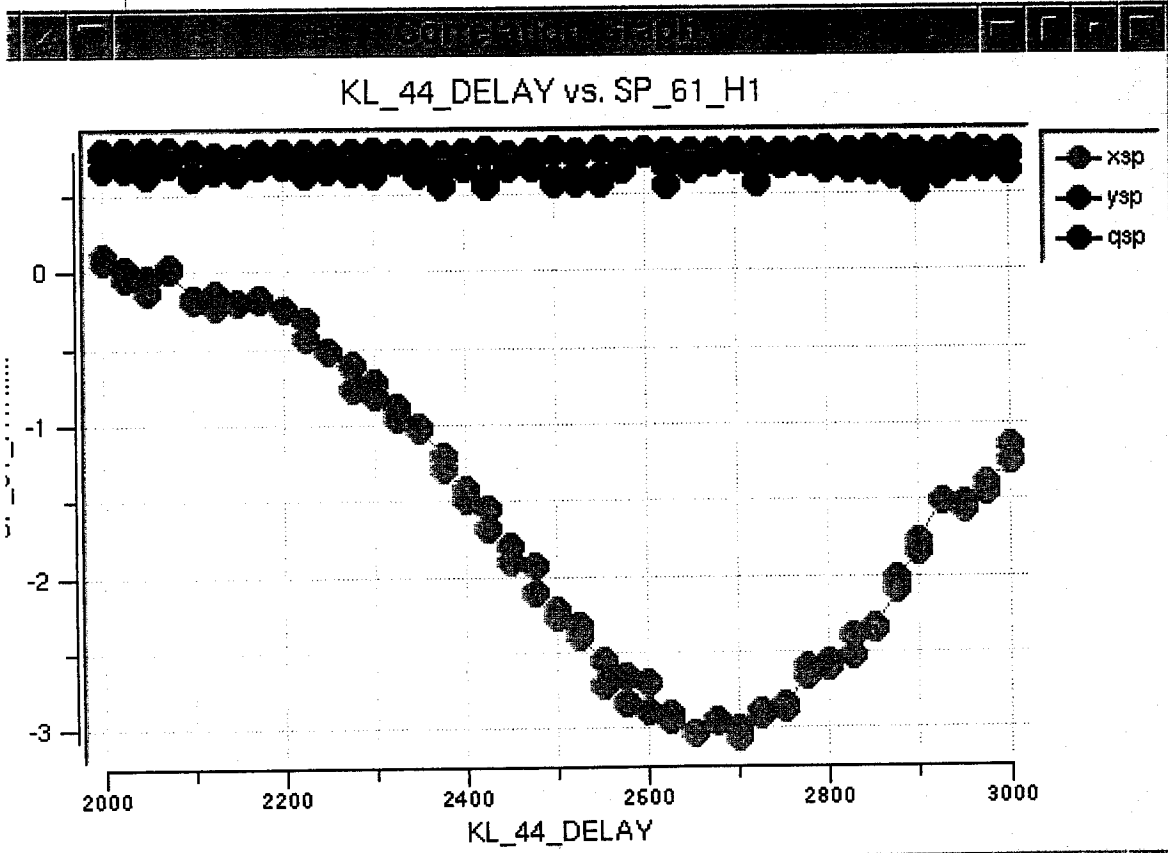
$$2 \times \frac{2.87727}{307.5} \times 1000 = 74.85 \text{ MeV}$$

$$\frac{74.85}{0.9622254} = 19.5 \text{ MV/m}$$



PHASE 150°

KL-44 - DELAY 2600 → 2650 にて

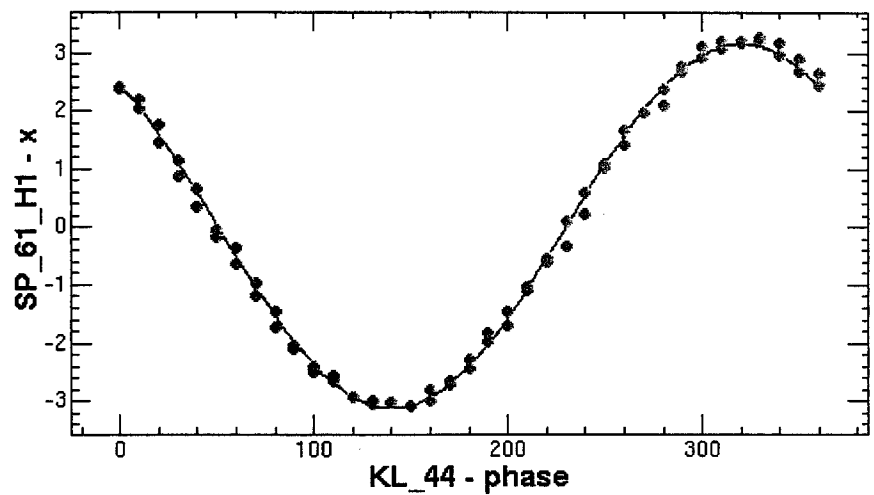


ChiSquare = 1.08654 Goodness = .47768

a = 3.14087 +/- .02030

c = 140.326 +/- .37217

d = .01005 +/- .01439



Function = (d+(a Cos[(.0174532925 (-180+x+(-c))])))

8×3.14087
 307.5
 $= 81.92$
 MV

Hard Copy

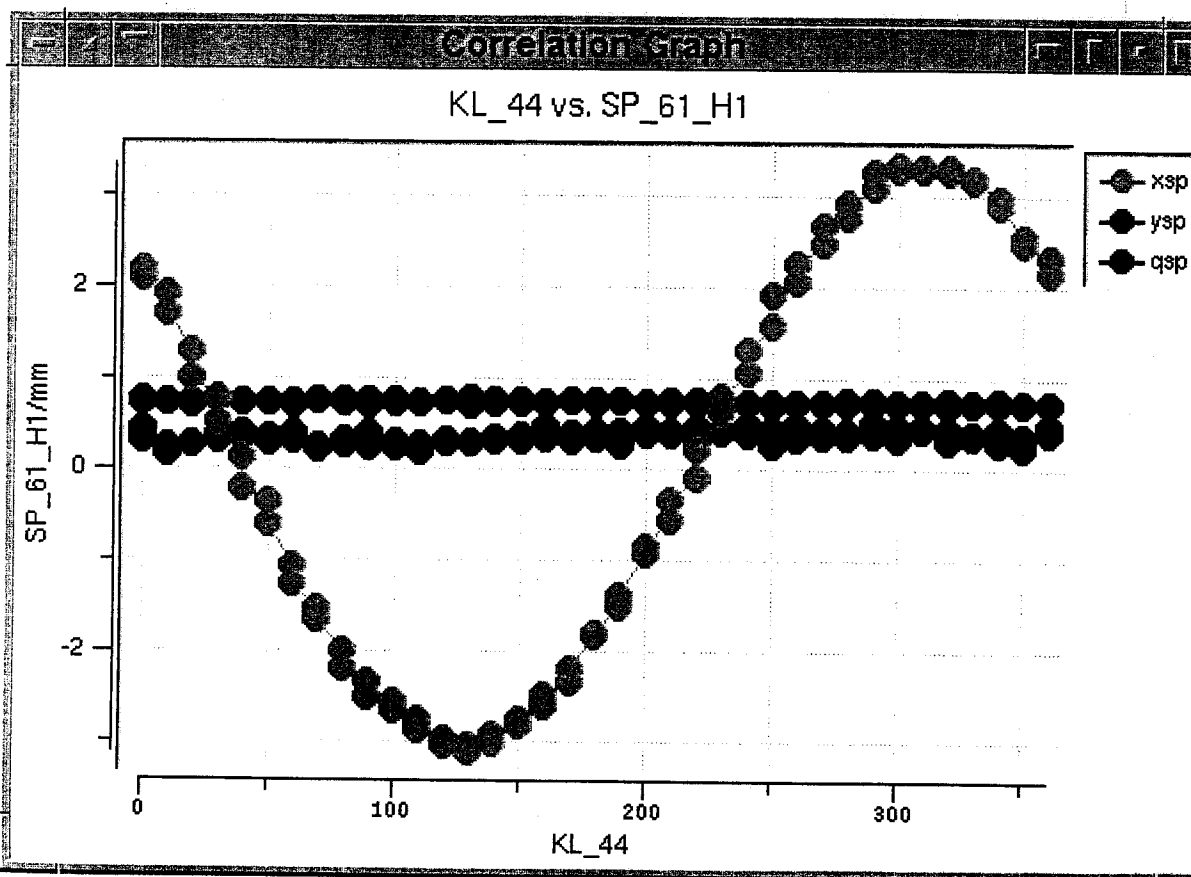
30

$E_s = 41.1$
~~41.0~~ kV

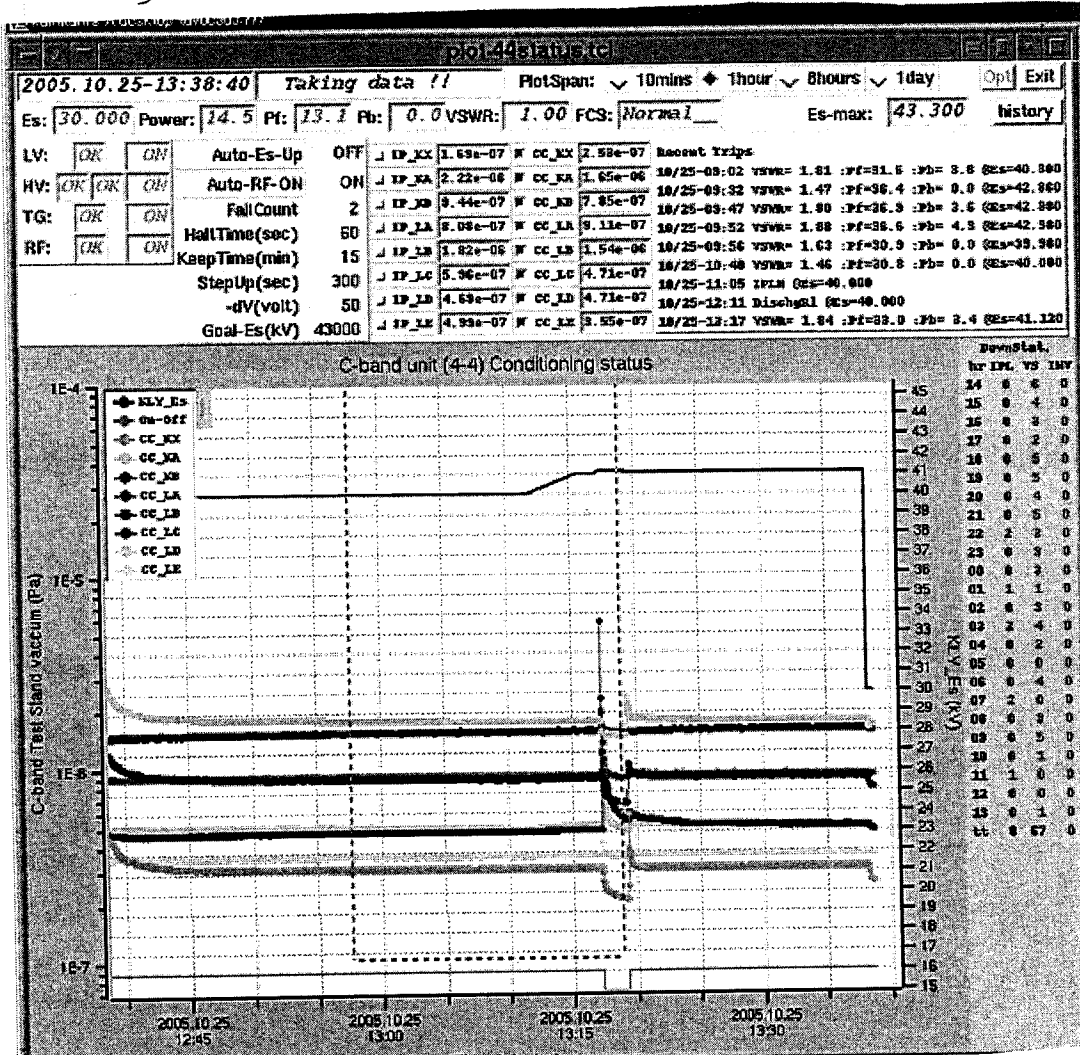
$\rightarrow E_{3.2 \text{ mm}}$

gain
 83.3 MV

KL_44_DELAY = 265

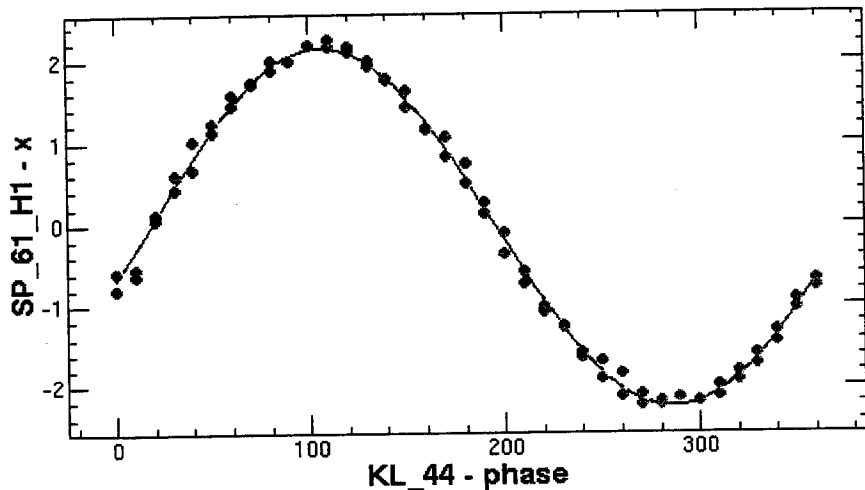


13:38 $E_s = 30 \text{ kV}$ DELAY 2657 $\Rightarrow 57.3 \text{ MV}$



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ChiSquare = .70182 Goodness = .47768
 a = 2.20348 +/- .01654 c = -2953.6 +/- .42080 d = -.06087 +/- .01157



Function = (d+(a Cos[(.0174532925 (-180+xx+(-c))])))