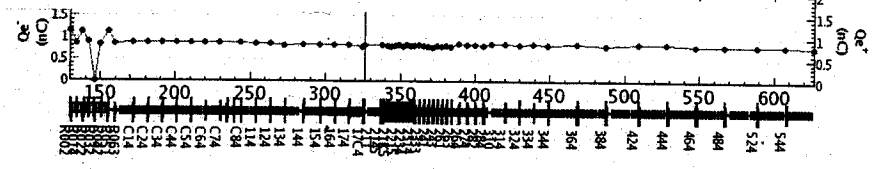
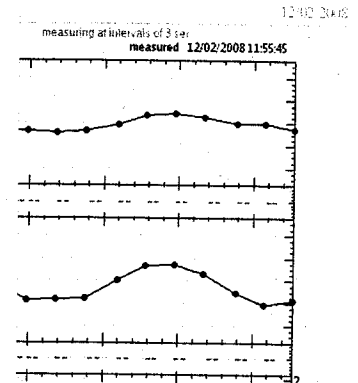
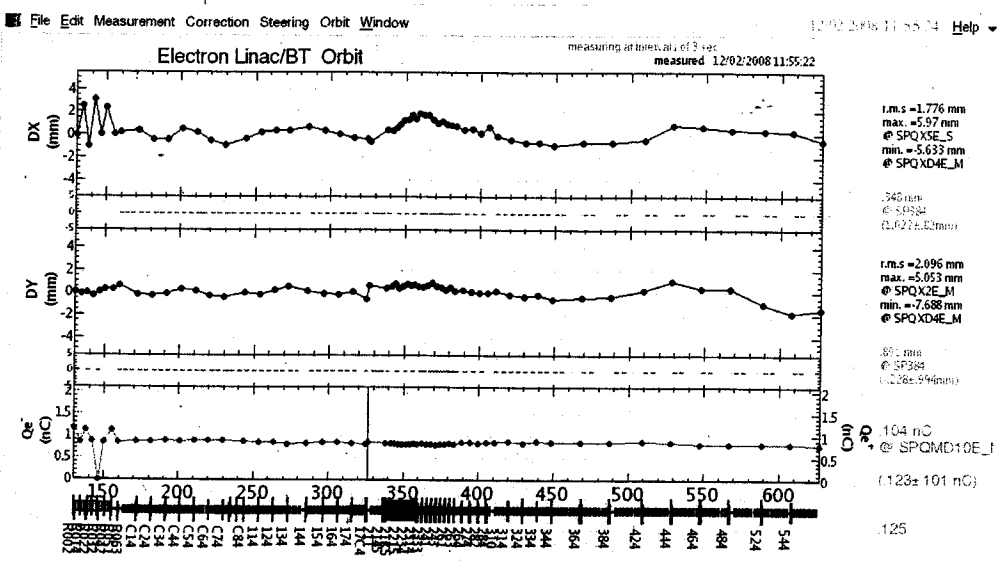


水平軌道の
変動は、
工場のモードに
同期している
(Jarcの軌道)

垂直軌道は
それとは別に
見えた

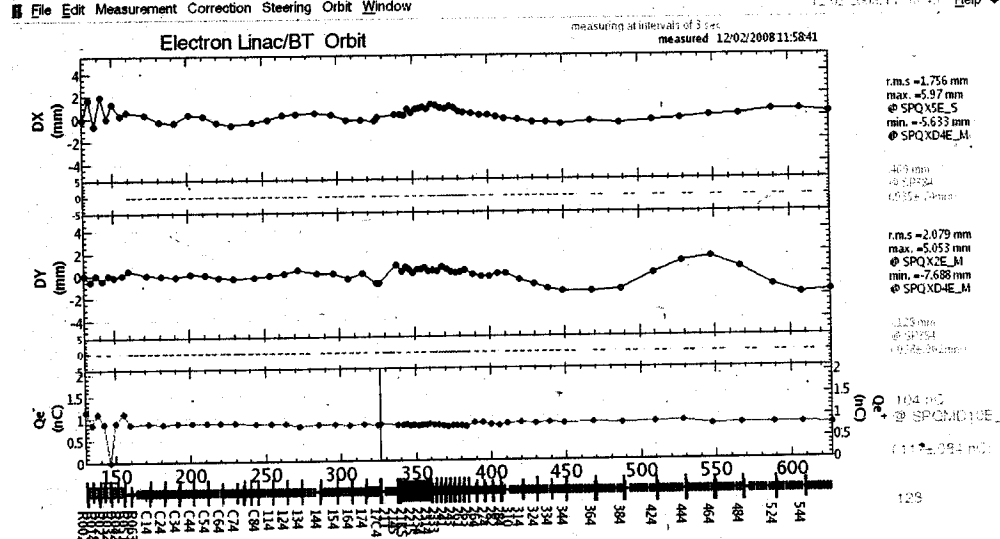
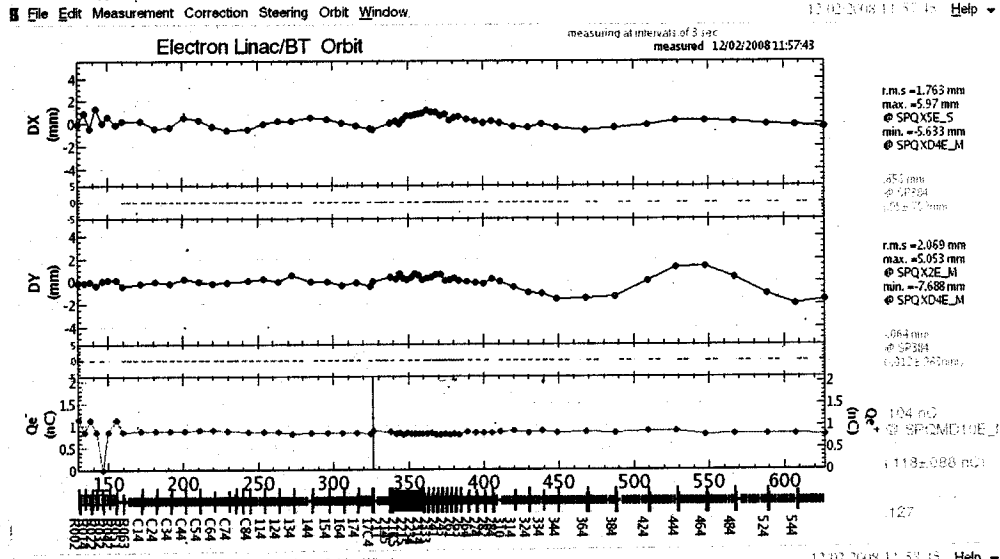
運転パラメータに可

運転パラメータでも揺れている



11:58

Target 交換



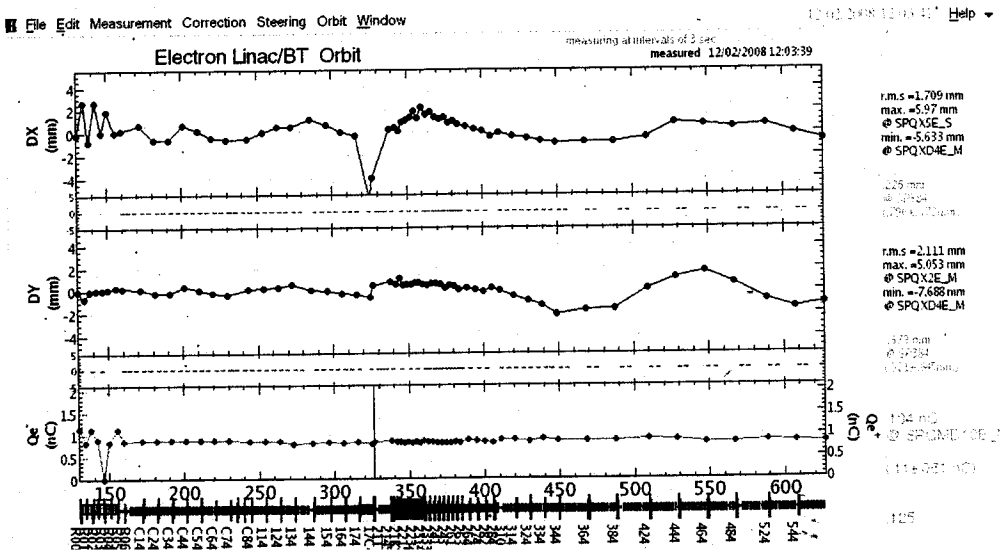
おしり変動

12:02

Target ~~は~~ bump off set ϕ 全2の Pulse St. ϕ set ϕ

12:03

Target PS 交換 FG = off



変動おしり (おしり)

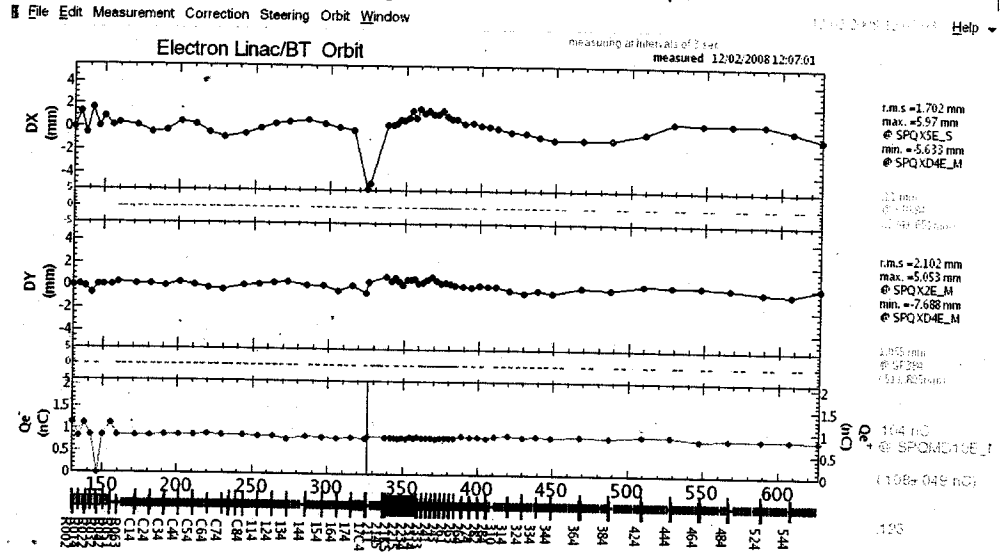
少しだけ

FG

12:06

Pulse Steering 終了後 FG off

軌道が
おそろへた



14:16

古川・権山 Pulse steering 調整のため 比レタの調整に配線作業中

① 「0.8 msec 2771299(2)の ~~調整~~ 調整は完了」

15:04

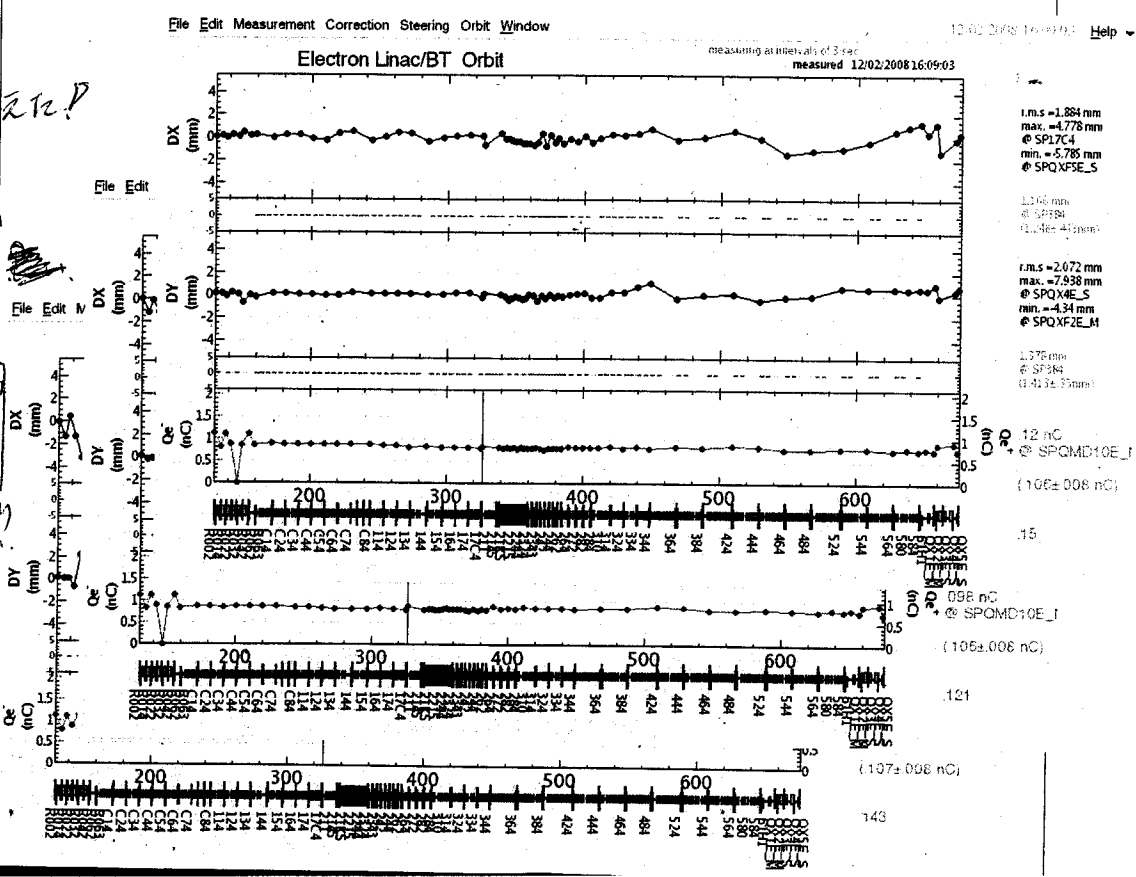
Pulse Steering 用 FG の offset E 値に調整済み

② 調整作業中 (権山)

調整済みの
Pulse St.
OA → 0.2A
に set 済み
kirk は OK

±0.2 A 以内
Set 済み

Timing
0.8 msec
おそろへた



e- BT matching

Study 1107X-9-

Px 17 C1 8.9 A

Px 17 C5 6.0

Px 2145 2.0

-1.5

Py 2145

Px 284 -2

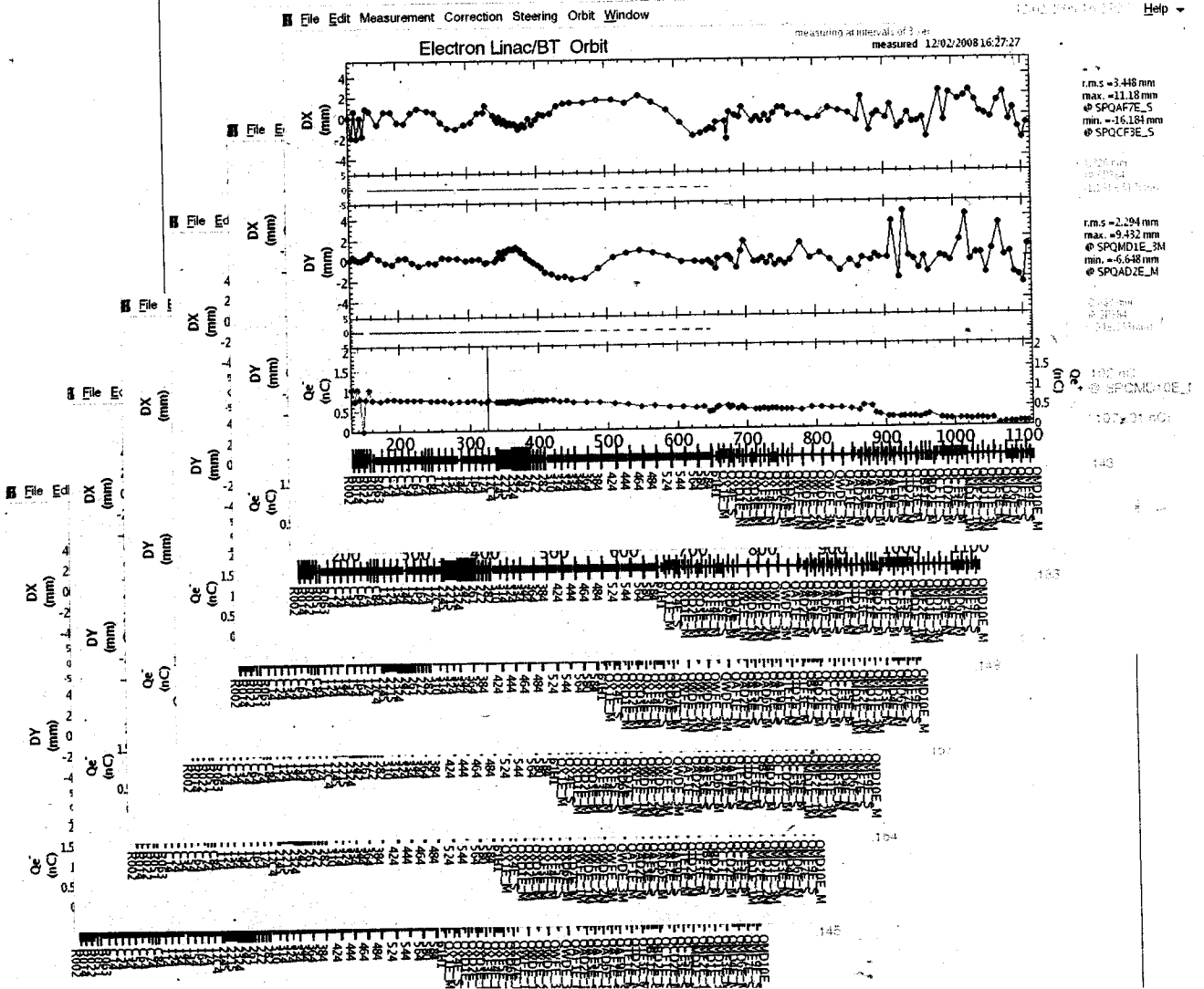
Py 284 0.5

Pz 384 0.2 ← O(A)

Py 384 0.5

~~Px 484~~ -1.5

Py 484 1.0



16:31

Px284 ~ Ky484 Set 0.2A

DC ST 2 軌區調整 3077 25

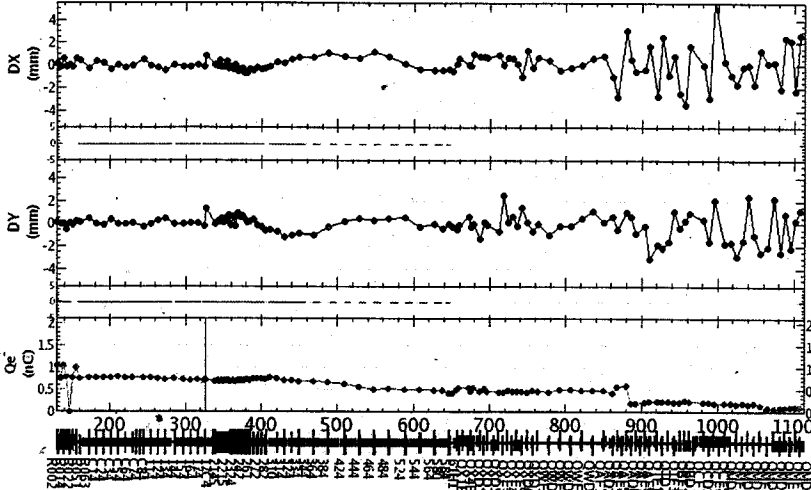
176

File Edit Measurement Correction Steering Orbit Window

12/02/2008 16:35:08 Help

Electron Linac/BT Orbit

measured 12/02/2008 16:35:08



r.m.s = 3.756 mm
 max. = 13.392 mm
 @ SPOAF7E_S
 min. = -17.493 mm
 @ SPQCF3E_S

Help

r.m.s = 2.511 mm
 max. = 7.754 mm
 @ SPQMD1E_3M
 min. = -9.681 mm
 @ SPQTD2E_M

7.96 mm
 4.877 mm
 6.549 mm
 7.93E_S

Help

r.m.s = 3.54 nC
 max. = 13.04 nC
 @ SPOAF7E
 min. = -16.68 nC
 @ SPQCF3E

108 nC
 @ SPQMD10E_I
 (108 ± 008 nC)

149

199

100

148

100

148

16:40:39 Target 抜 , Target bump off 軌區調整 (16:42)

177

16:52

F.G off.

16:54:30 pulse ST 電源 off.

書込
変動

KEKB 閉止後、各動は小=為、
KEKB 閉止後、各動は小=為、

(e)

Matching Study parameter と load.

178

18:00

運転パラメータでは変動小

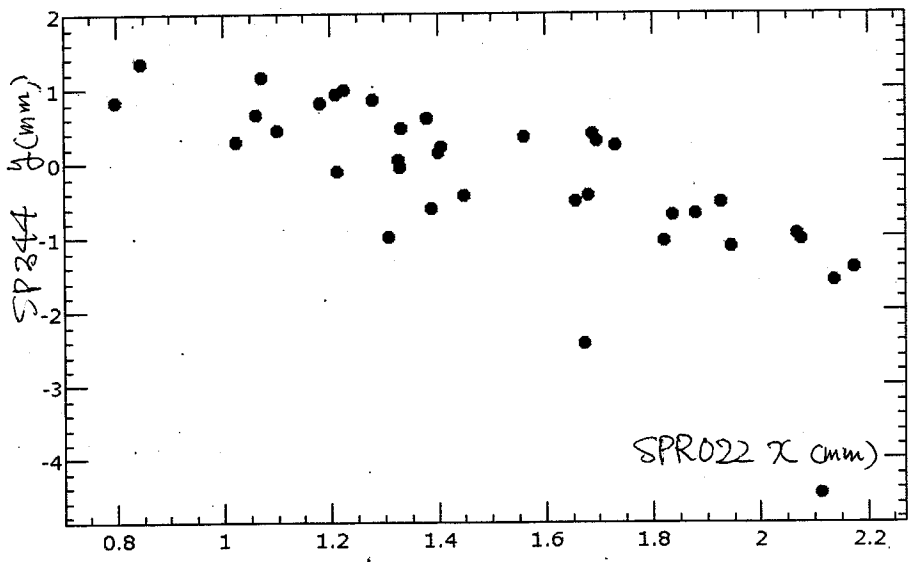
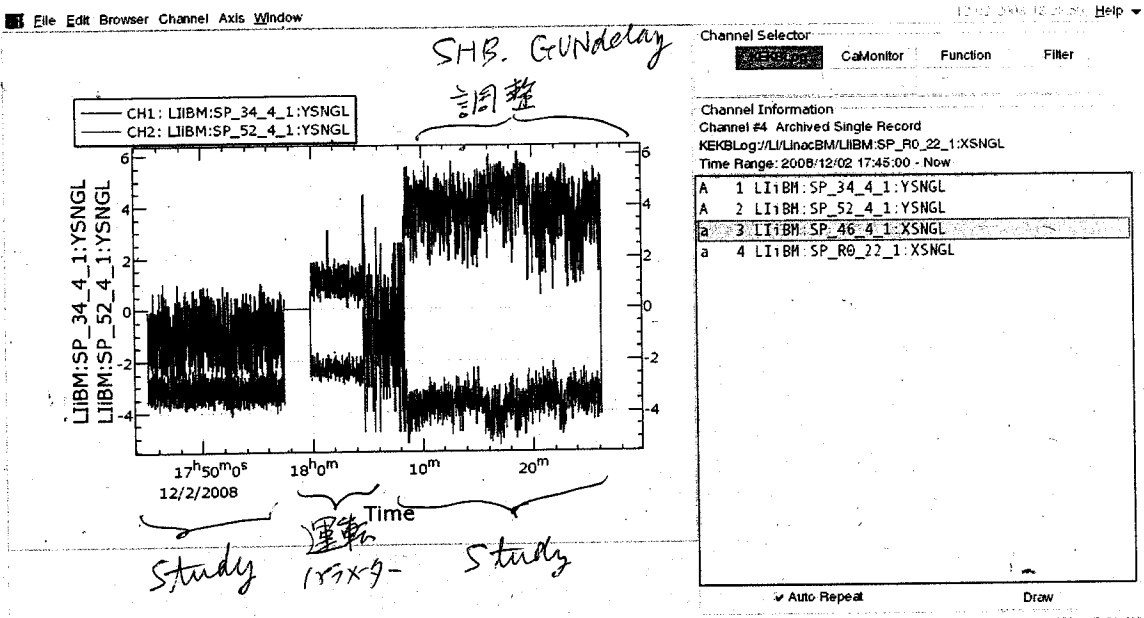
18:08

DC Magnet, Pulse steering と file と load
やはり変動大きくなる。

18:20

SHB と調整
GUN delay と調整
今の一番良い。

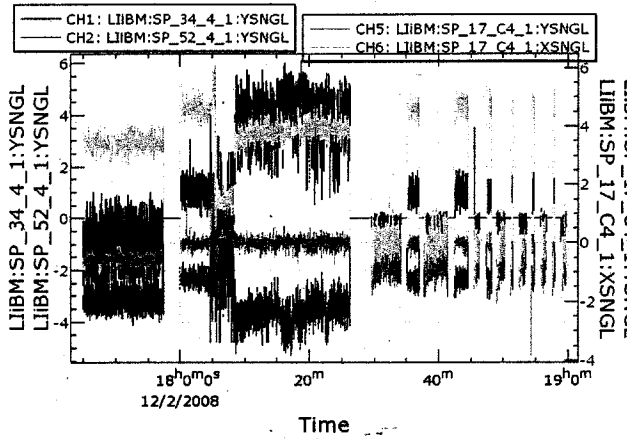
運転パラメータ



相関がある

mode
Study dispersion 現象

Edit Browser Channel Axis Window



Channel Selector
CaMonitor Function Filter

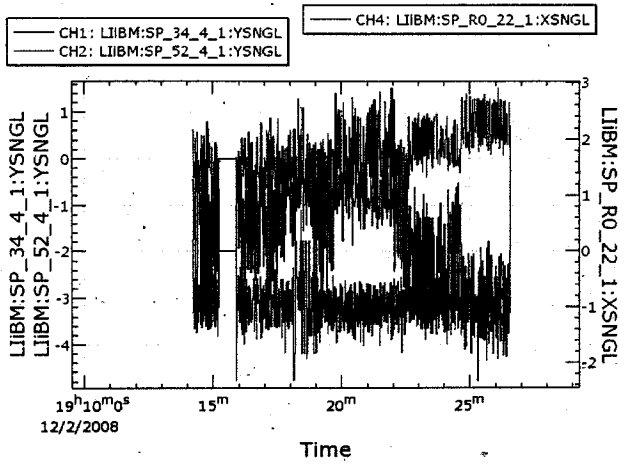
Channel Information
Channel #6 Archived Single Record
KEKLog://L/LinacBM/LIBM:SP_17_C4_1:XSNGL
Time Range: 2008/12/02 17:45:00 - Now

A	1	LIiBH:SP_34_4_1:YSNGL
A	2	LIiBH:SP_52_4_1:YSNGL
a	3	LIiBH:SP_46_4_1:XSNGL
a	4	LIiBH:SP_R0_22_1:XSNGL
A	5	LIiBH:SP_17_C4_1:YSNGL
A	6	LIiBH:SP_17_C4_1:XSNGL

I Are a Energy

- 7.6446
- 7.646
- 7.648
- 7.642
- 7.640

Edit Browser Channel Axis Window

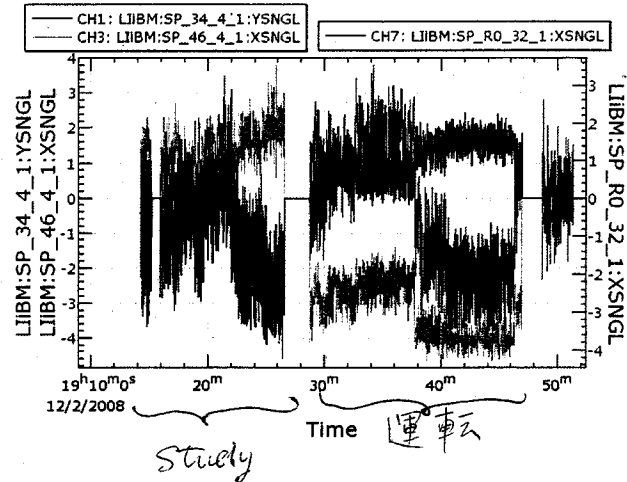


Channel Selector
CaMonitor Function Filter

Channel Information
Channel #6 Archived Single Record
KEKLog://L/LinacBM/LIBM:SP_17_C4_1:XSNGL
Time Range: 2008/12/02 19:10:00 - Now

A	1	LIiBH:SP_34_4_1:YSNGL
A	2	LIiBH:SP_52_4_1:YSNGL
a	3	LIiBH:SP_46_4_1:XSNGL
A	4	LIiBH:SP_R0_22_1:XSNGL
a	5	LIiBH:SP_17_C4_1:YSNGL
a	6	LIiBH:SP_17_C4_1:XSNGL

Edit Browser Channel Axis Window



Channel Selector
KEKLog CaMonitor Function Filter

Channel Information
Channel #1 Archived Single Record
KEKLog://L/LinacBM/LIBM:SP_34_4_1:YSNGL
Time Range: 2008/12/02 19:10:00 - Now

A	1	LIiBH:SP_34_4_1:YSNGL
a	2	LIiBH:SP_52_4_1:YSNGL
A	3	LIiBH:SP_46_4_1:XSNGL
a	4	LIiBH:SP_R0_22_1:XSNGL
a	5	LIiBH:SP_17_C4_1:YSNGL
a	6	LIiBH:SP_17_C4_1:XSNGL
A	7	LIiBH:SP_R0_32_1:XSNGL

.Study

$$n_g = \frac{3.0 \text{ mm}}{4.8 \times 10^{-3} \text{ m}} = 0.63$$

運転云

$$n_g = \frac{1.0 \text{ mm}}{4.8 \times 10^{-3} \text{ m}} = 0.2$$

19:30

運転 mode τ dispersion 測定

180

20:11

運転軌道に近付いた

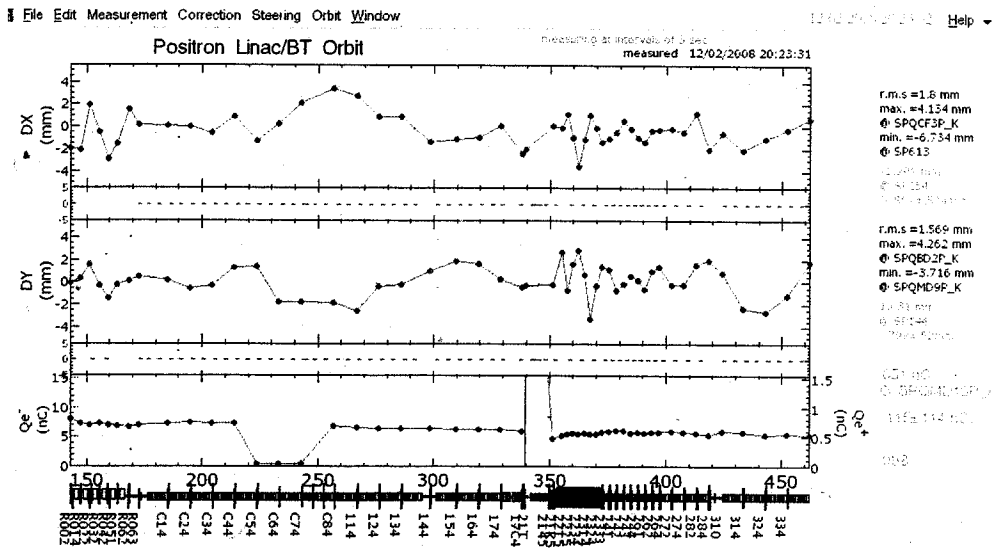
(e^+)

e^+ の軌道に近付く

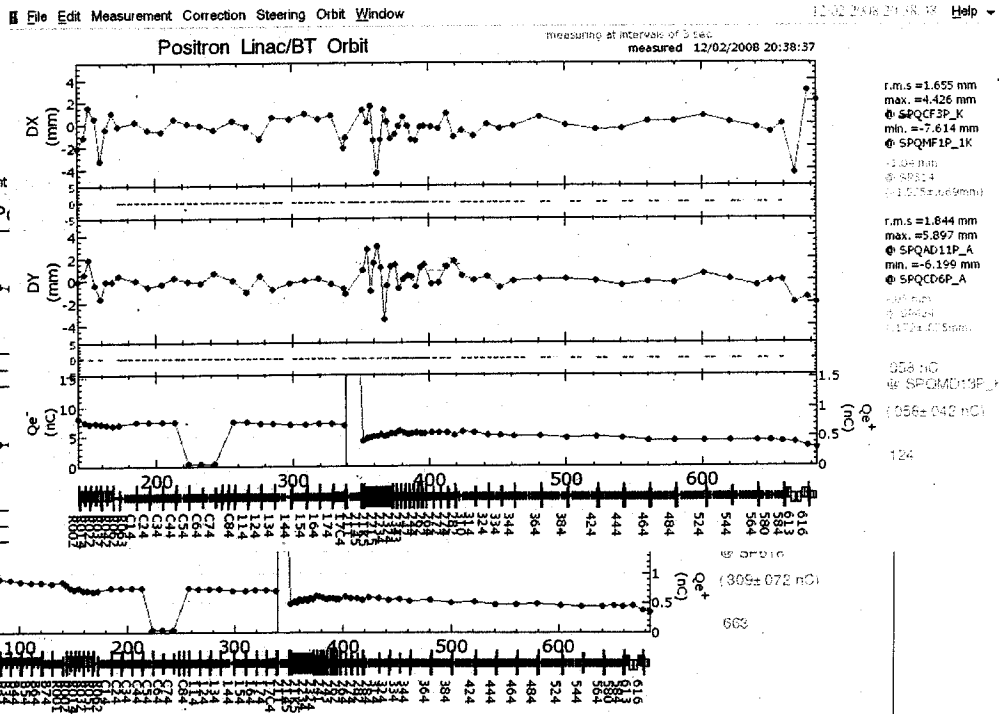
BTP の Study " BTP 11 27-2008-14:28:30 "

運転 / Q BTP#2-02-2008-20:18:45 "

S+ BTP12-02-2008-20:19:16 " I-save



軌道補正



LINAC { QM: " 20081202-20:37:50 "
SA: " " -20:38:14 " I-save