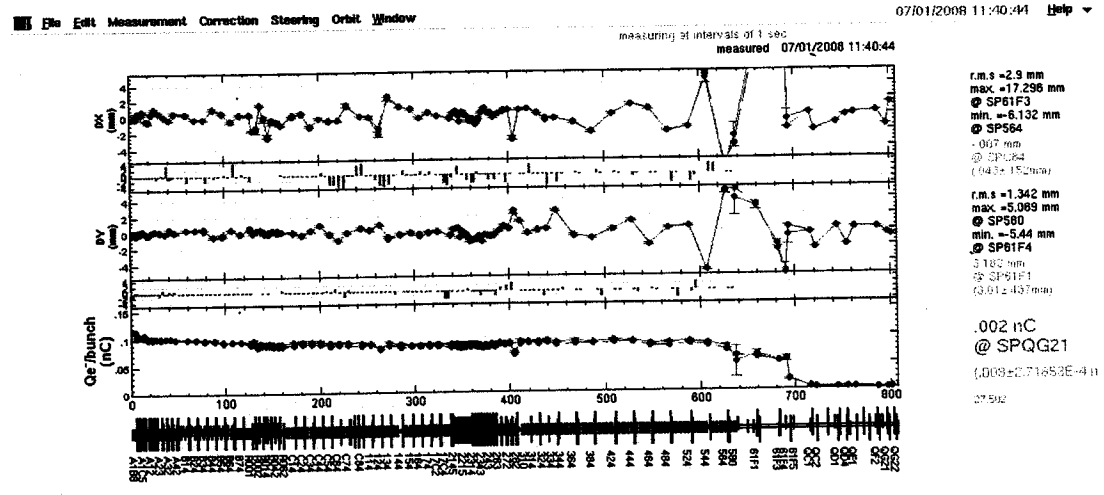


2008.7.

1
 pf/keksbe 同時入射 29行
 孔あき Target 透過
 0.4-E PF用 に 切り替る. STは 8G用 と同じ

紙谷 大西 古川
 小川 南地 飯田

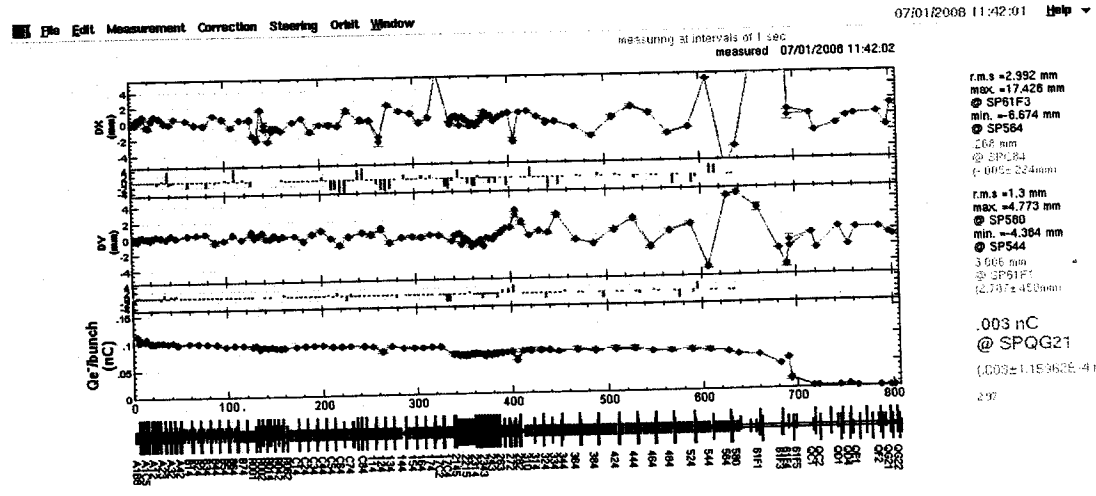


0.088
 244 0.087
 Bump 0.076
 Gen 0.058

mode v a* e* range DX Auto Fix (5) DV Auto Fix (5) Q Auto Fix (2) e/h* 4 Replot
 Clear Statistics
 meas -> ref stat -> ref
 SX431 0.20 A

Q = 0.087 nC

~~Bump~~ Bump ON



Q = 0.076 nC

mode v a* e* range DX Auto Fix (5) DV Auto Fix (5) Q Auto Fix (2) e/h* 4 Replot
 Clear Statistics
 meas -> ref stat -> ref
 SX431 0.20 A

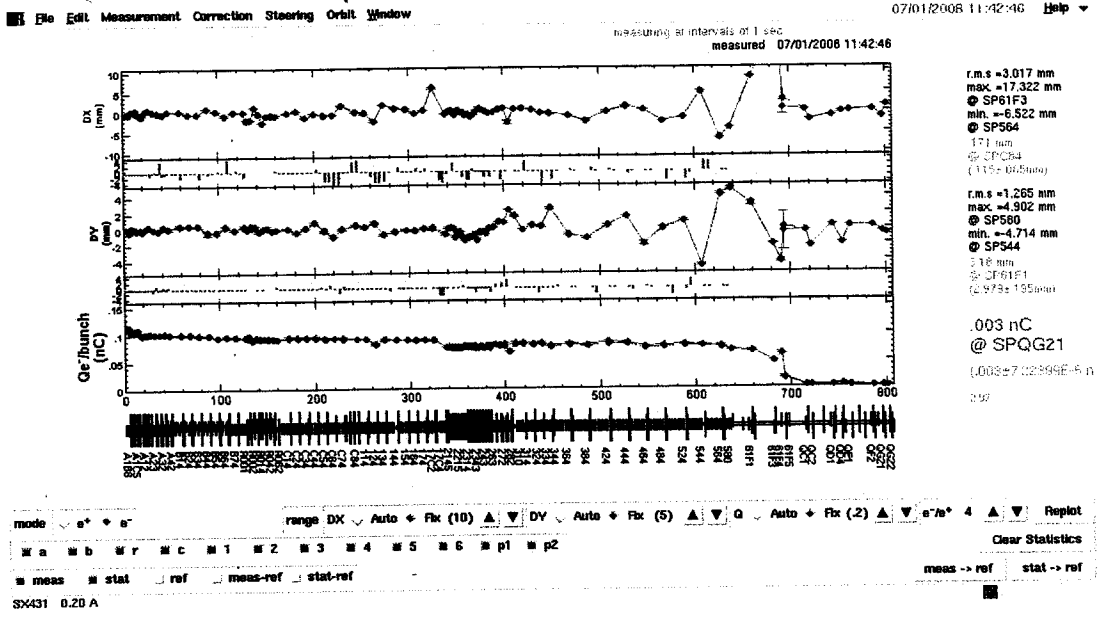
スティング設定値 Inc 8Gの E-42 調整したもの

Buttons: Read, Save, File, Diff, Select, Clear, Set Magnet

File paths:
 /mnt/hadatal/b/data/LINAC/CG/magnet/2008/07/skbe20080701-11:25:01
 /mnt/hadatal/b/data/LINAC/CG/magnet/2008/07/skbe20080701-11:25:06

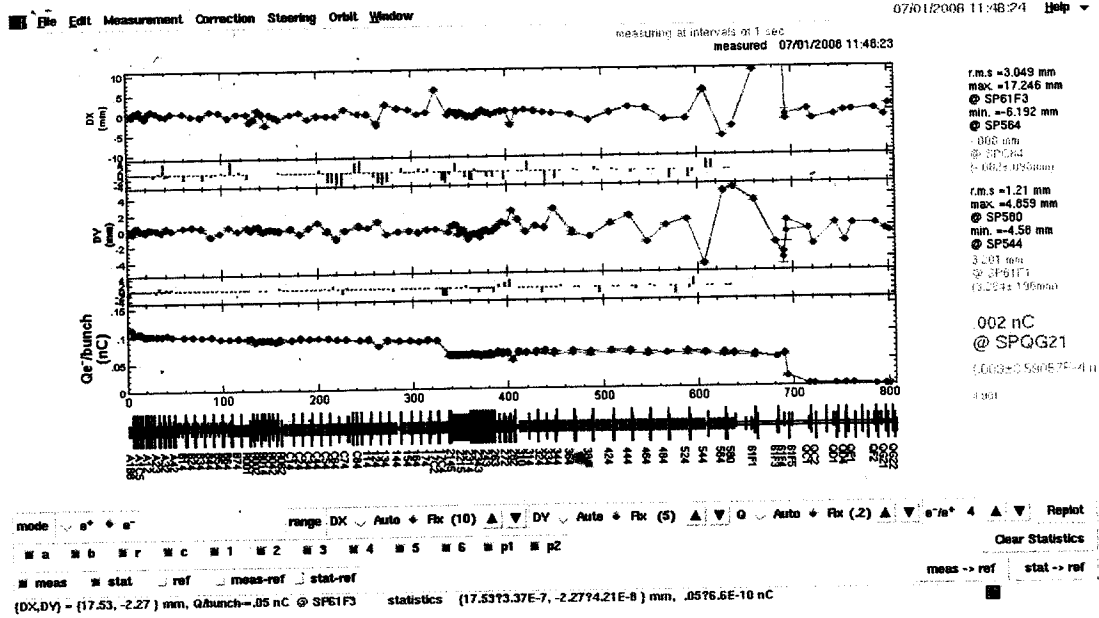
Save file to: Adata/LINAC/CG/magnet/2008/07/skbe20080701-11:25:06

同く ~~SPQ~~ Bump ON (縦向きに測定)



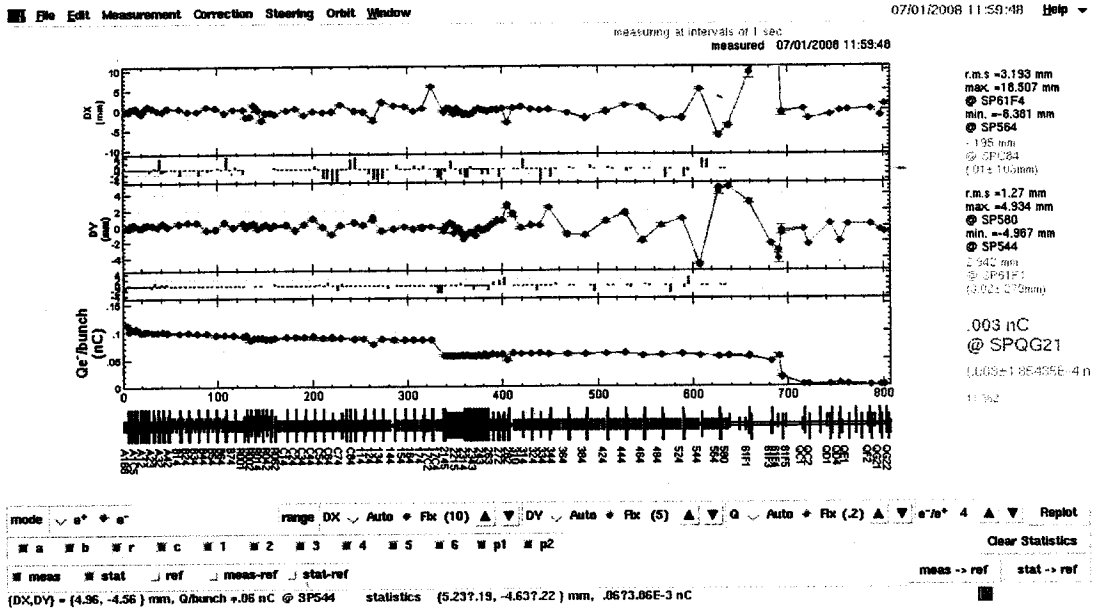
$Q = 0.058 nC$

Bump ON 29-First IN



$Q = 0.058 nC$

① mci	② 21K5
8.0	0.051
8.2	0.055
8.4	0.061 ~ 0.059
8.6	0.057
8.8	0.056
9.0	0.056
8.5	0.058



13:40

pt 3079-以降 軌道補正.

12:00

A1-GUN Grid emission 問題 (TMA)

A1-Gun modulator の Timing ずれ

3 nsec ずれと スリッパに いたから..

バッチ-の 後 ~~8~~
(A1-B8)

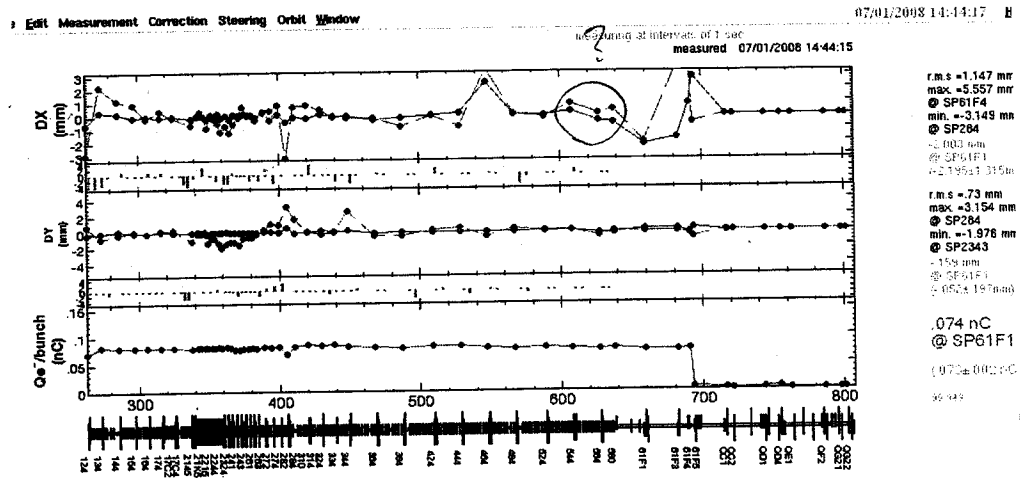
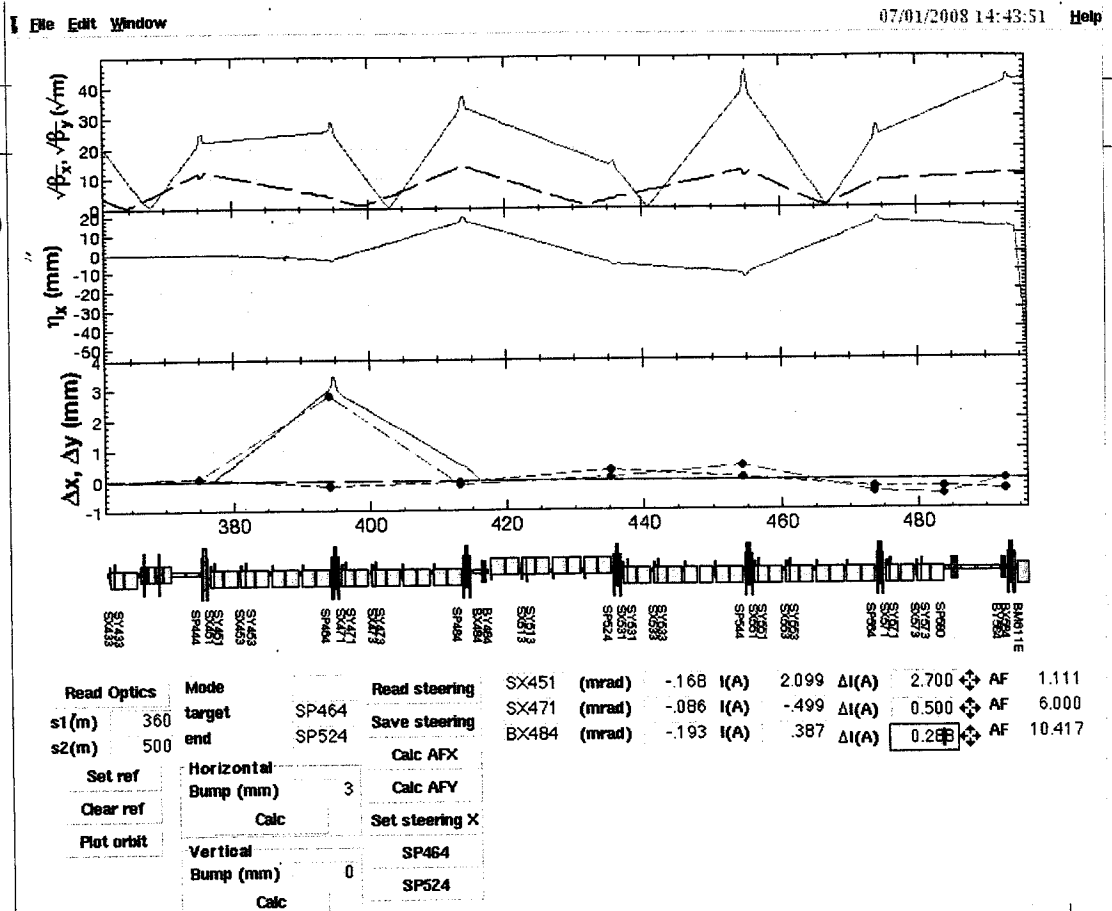
LINAC 61-H1 ずれ 見えたから.. OK!

13:45

4.5079- Bump 作り.

SP464

X

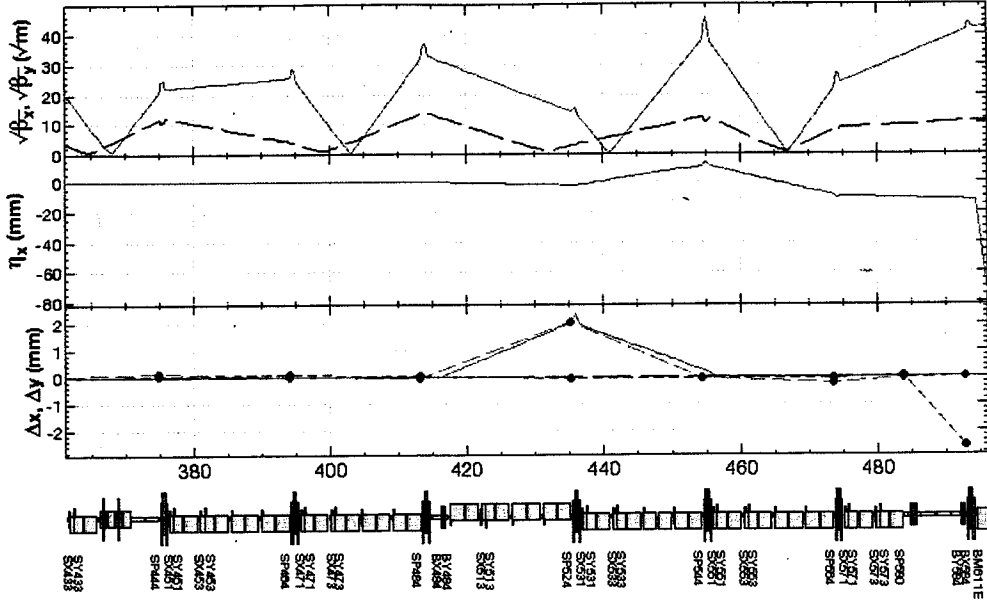


バックの、南側
 1度南じて、打て出さく3.
 進たの、次に進む。

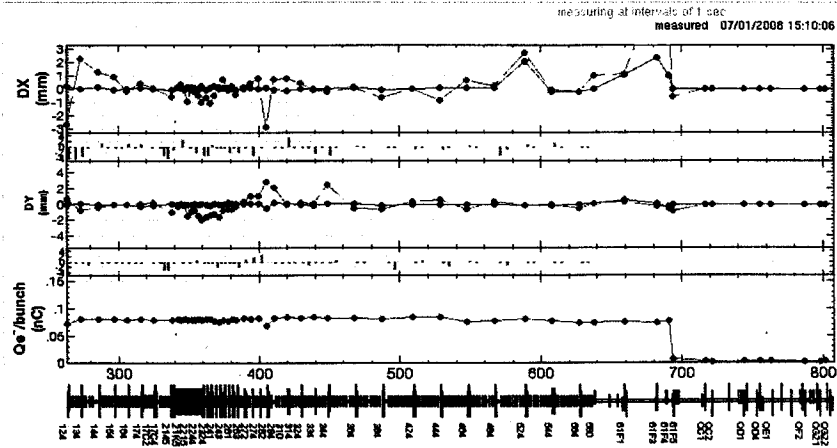
5

SP524

X



Read Optics	Mode	Read steering	BX484 (mrad)	-1.05	I(A)	282	ΔI(A)	0.183	AF	10.929
s1(m)	target	Save steering	SX531 (mrad)	-0.83	I(A)	-3.083	ΔI(A)	0.720	AF	2.778
s2(m)	end	Calc AFX	SX551 (mrad)	-1.25	I(A)	.751	ΔI(A)	1.049	AF	1.907
Set ref	Horizontal	Calc AFY								
Clear ref	Bump (mm)	Calc AFY								
Plot orbit	Calc	Set steering X								
	Vertical	SP464								
	Bump (mm)	SP524								
	Calc									



r.m.s = 1.408 mm
 max = 7.806 mm
 @ SP61F4
 min = -2.884 mm
 @ SP284
 1.122 mm
 @ SP61F1
 (-0.8632, 0.07mm)

r.m.s = 737 mm
 max = 2.787 mm
 @ SP284
 min = -1.975 mm
 @ SP2343
 722 mm
 @ SP61F1
 (-0.8642, 0.7mm)

0.75 nC
 @ SP61F1
 (0.72 ± 0.01 nC)

15:30

SP334 の Quad-BPM

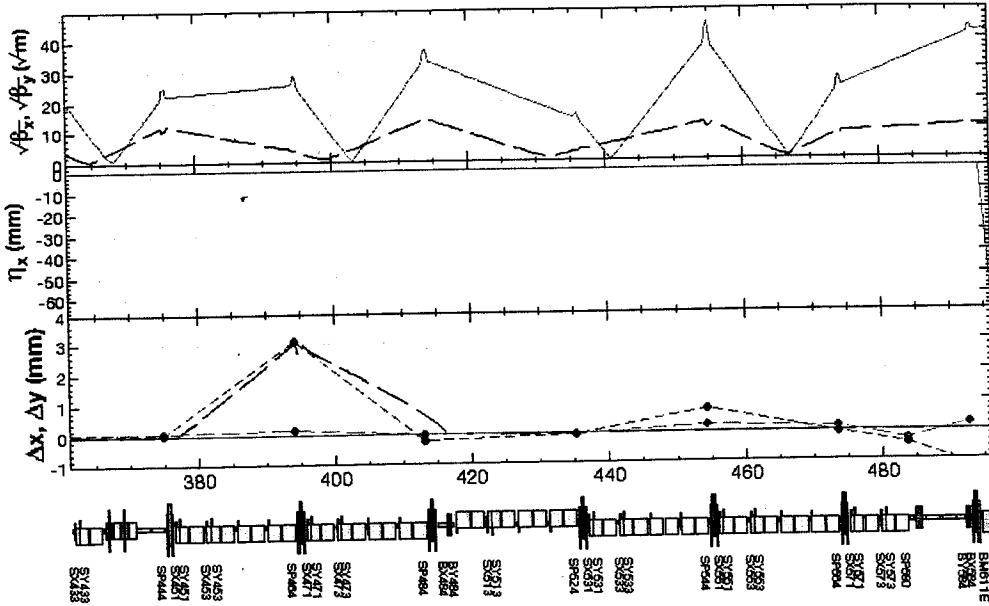
Y方向の動きが、延期。

SP464

Y

File Edit Window

07/01/2008 16:16:47 Help

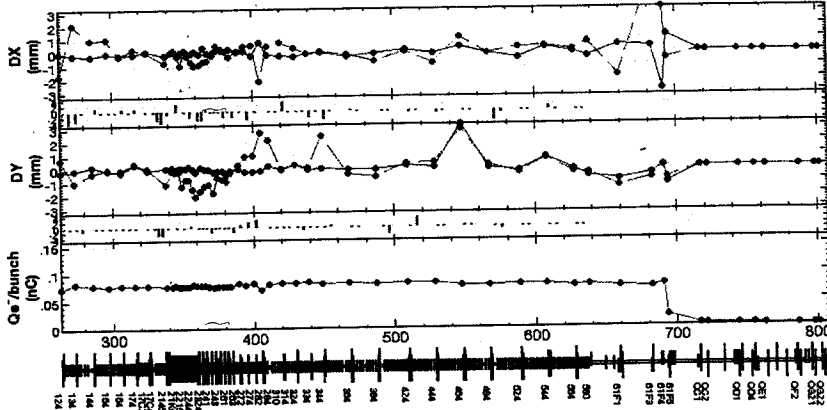


Read Optics	Mode	Read steering	SX451 (mrad)	0.000 I(A)	-600 ΔI(A)	0.000	AF	1.111
s1(m) 360	target SP464	Save steering	SX471 (mrad)	0.000 I(A)	-1.000 ΔI(A)	0.000	AF	6.000
s2(m) 500	end SP524	Calc AFX	BX484 (mrad)	0.000 I(A)	0.099 ΔI(A)	0.000	AF	10.417
Set ref	Horizontal	Calc AFY	SY451 (mrad)	-1.68 I(A)	3.303 ΔI(A)	2.700	AF	1.111
Clear ref	Bump (mm)	Calc AFY	SY471 (mrad)	-0.96 I(A)	-600 ΔI(A)	0.800	AF	3.750
Plot orbit	Calc	Set steering X	BY484 (mrad)	-1.99 I(A)	0.267 ΔI(A)	0.299	AF	10.067
	Vertical	Set steering Y						
	Bump (mm)	Calc						

Edit Measurement Correction Steering Orbit Window

07/01/2008 16:22:37 Help

measuring at intervals of 1 sec
measured 07/01/2008 16:22:37



r.m.s = 994 mm
max = 5.482 mm
@ SP61F3
min = -2.181 mm
@ SP284
-1.776 mm
@ SP61F1
(-426 ± 393 mm)

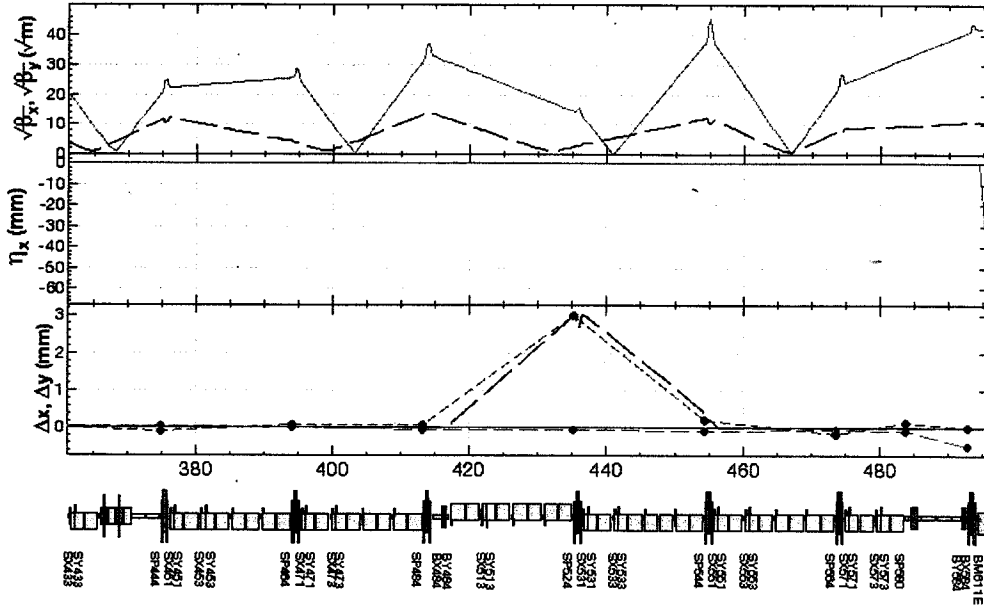
r.m.s = 626 mm
max = 2.913 mm
@ SP464
min = -2.083 mm
@ SP2343
-1.443 mm
@ SP61F1
(-504 ± 693 mm)

074 nC
@ SP61F1
(0.70 ± 0.02 nC)

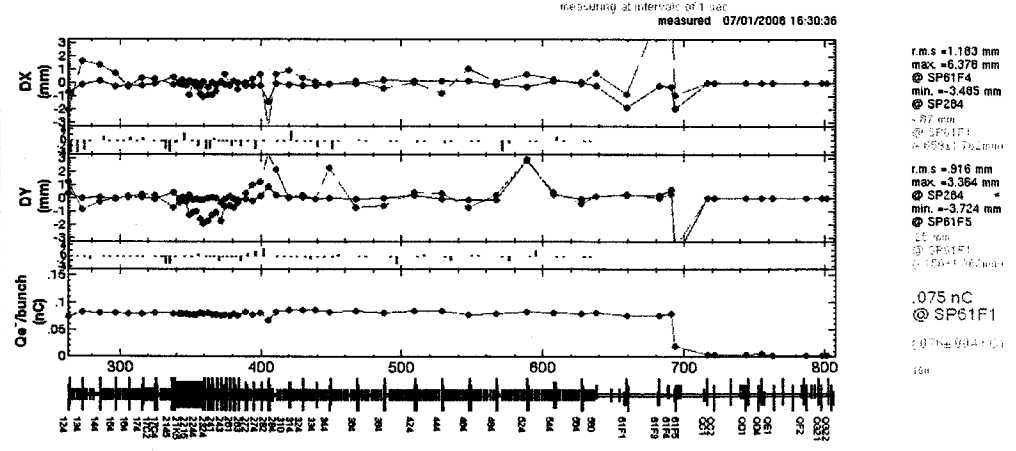
7

SP524

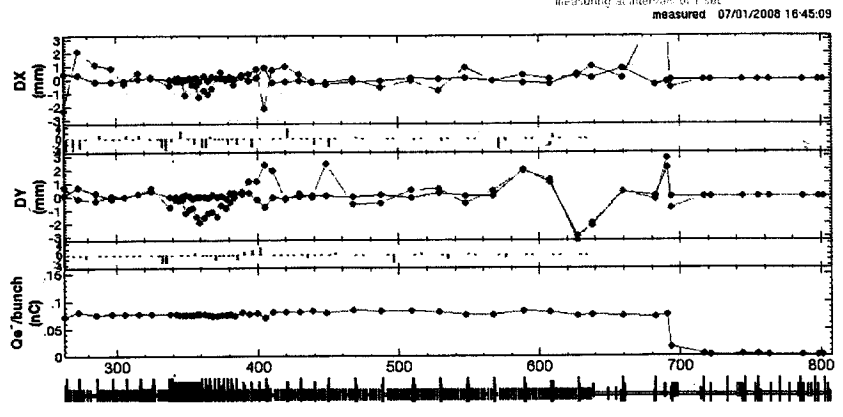
Y



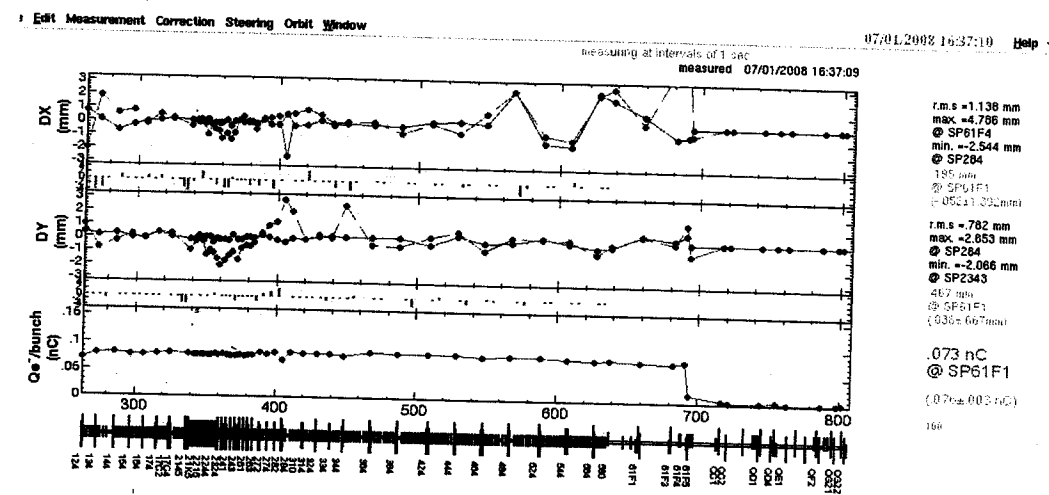
Read Optics	Mode	Read steering	BX484 (mrad)	0.000 I(A)	.099 ΔI(A)	0.000 AF	10.929
s1(m) 360	target SP524	Save steering	SX531 (mrad)	0.000 I(A)	-3.803 ΔI(A)	0.000 AF	2.778
s2(m) 500	end SP564	Calc AFX	SX551 (mrad)	0.000 I(A)	-2.999 ΔI(A)	0.000 AF	1.907
Set ref	Horizontal	Calc AFY	BY484 (mrad)	-1.161 I(A)	.243 ΔI(A)	0.274 AF	10.949
Clear ref	Bump (mm) 0	Set steering X	SY531 (mrad)	.019 I(A)	-1.720 ΔI(A)	-0.720 AF	-4.167
Plot orbit	Calc	Set steering Y	SY551 (mrad)	-1.193 I(A)	1.752 ΔI(A)	1.750 AF	1.714
	Vertical						
	Bump (mm) 3						
	Calc						



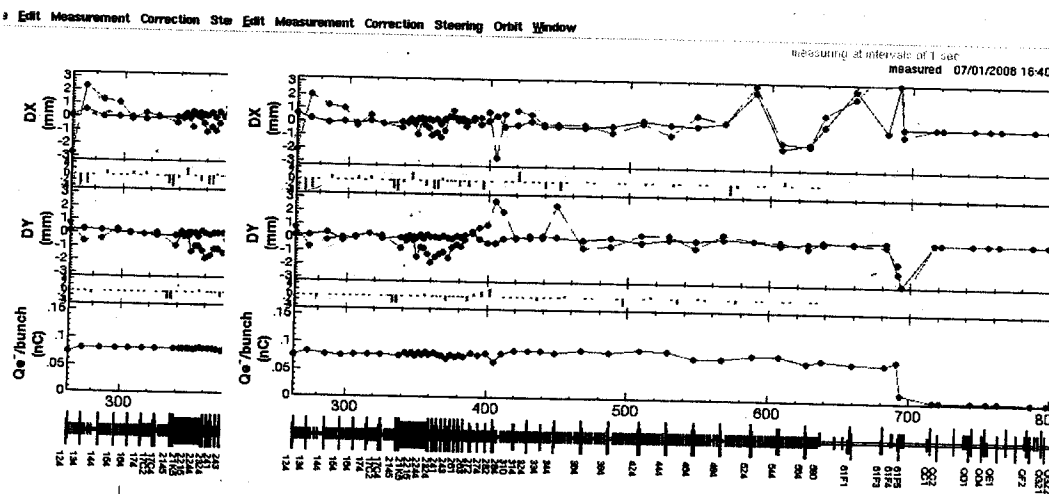
BY484
+0.2A



16:35	SX471	\bar{c} single kick	$\pm 2A$
16:40	BX484	"	$\pm 0.2A$
16:43	SY471	"	$\pm 2A$
16:45	BY484	"	$\pm 0.2A$

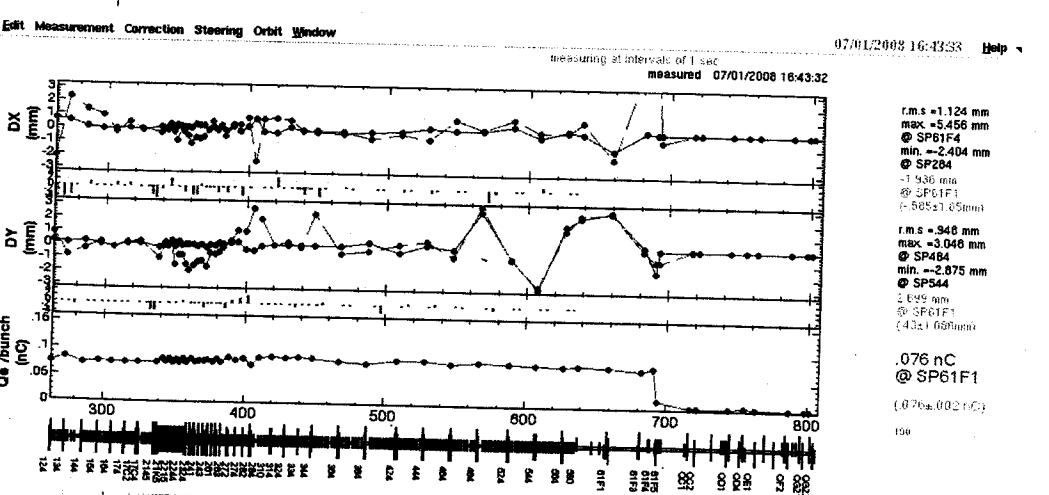


SX471 + 2A



BX484 + 0.2A

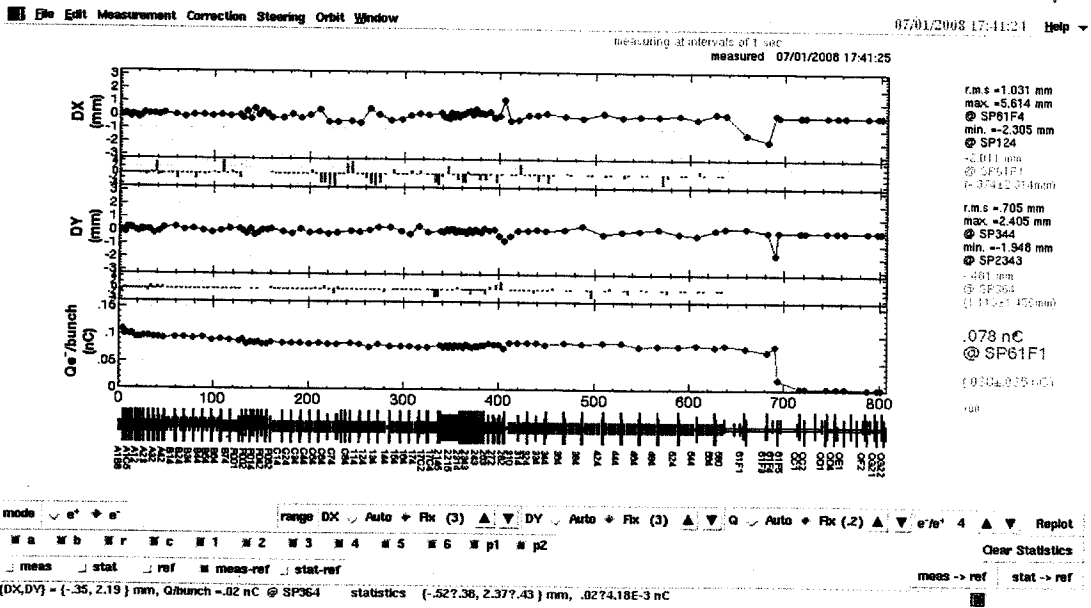
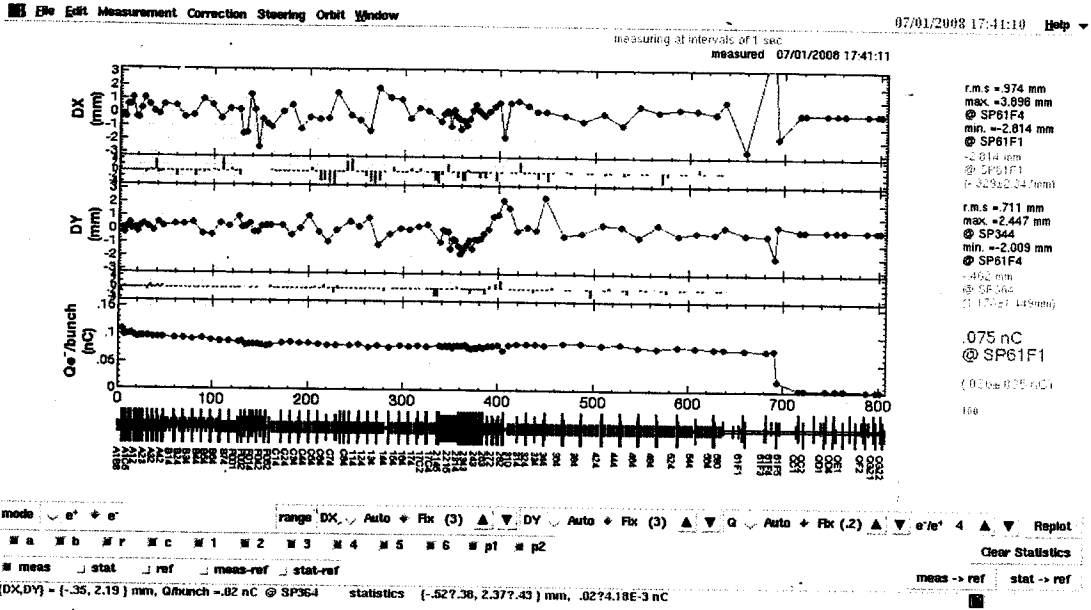
SX471
-2A



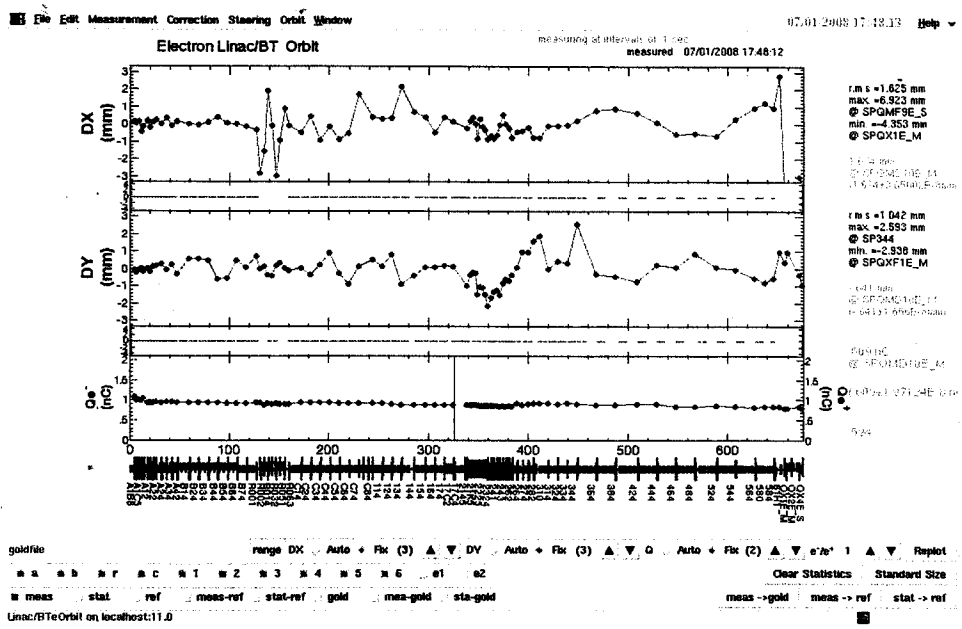
SY471 + 2A

PF-AIビームの軌道と束程度を示した状態

17:41



KEKB E-4 (スプリングは先になるべく orbit をおとした状態)



KEKB E-4 (PFAI用 ST 値を出力した状態)

